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Kähler-Einstein metrics on log del Pezzo surfaces in weighted projective 3-spaces


<http://aif.cedram.org/item?id=AIF_2001__51_1_69_0>
A log del Pezzo surface is a projective surface with quotient singularities such that its anticanonical class is ample. Such surfaces arise naturally in many different contexts, for instance in connection with affine surfaces (Miyanishi [Mi]), moduli of surfaces of general type (Alexeev [Al2]), 3 and 4 dimensional minimal model program (Alexeev [Al1]). They also provide a natural testing ground for existence results of Kähler-Einstein metrics. The presence of quotient singularities forces us to work with orbifold metrics, but this is usually only a minor inconvenience. Log del Pezzo surfaces with a Kähler-Einstein metric also lead to Sasakian-Einstein 5-manifolds by Boyer-Galicki ([BoGa]).

In connection with [DeKo], the authors ran a computer program to find examples of log del Pezzo surfaces in weighted projective spaces. The program examined weights up to a few hundred and produced 3 examples of log del Pezzo surfaces where the methods of Demailly-Kollár ([DeKo], §6), proved the existence of a Kähler-Einstein metric.

The aim of this paper is twofold. First, we determine the complete list of anticanonically embedded quasi smooth log del Pezzo surfaces in

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weighted projective 3-spaces. Second, we improve the methods of Demailly-Kollár ([DeKo], 6.10), to prove that many of these admit a Kähler-Einstein metric. The same method also proves that some of these examples do not have tigers (in the colorful terminology of Keel-McKernan [KeMcK]).

Higher dimensional versions of these results will be considered in a subsequent paper.

**Definition 1.** For positive integers $a_i$ let $\mathbb{P}(a_0, a_1, a_2, a_3)$ denote the weighted projective 3-space with weights $a_0 \leq a_1 \leq a_2 \leq a_3$. (See Dolgachev ([Do]) or Fletcher ([Fl]) for the basic definitions and results.) We always assume that any 3 of the $a_i$ are relatively prime. We frequently write $\mathbb{P}$ to denote a weighted projective 3-space if the weights are irrelevant or clear from the context. We use $x_0, x_1, x_2, x_3$ to denote the corresponding weighted projective coordinates. We let $(i, j, k, \ell)$ be an unspecified permutation of $(0, 1, 2, 3)$. $P_i \in \mathbb{P}(a_0, a_1, a_2, a_3)$ denotes the point $(x_j = x_k = x_\ell = 0)$. The affine chart where $x_i \neq 0$ can be written as

$$\mathbb{C}^3 (y_j, y_k, y_\ell)/\mathbb{Z}_{a_i} (a_j, a_k, a_\ell).$$

This shorthand denotes the quotient of $\mathbb{C}^3$ by the action

$$(y_j, y_k, y_\ell) \mapsto (\epsilon^{a_j} y_j, \epsilon^{a_k} y_k, \epsilon^{a_\ell} y_\ell)$$

where $\epsilon$ is a primitive $a_i$th root of unity. The identification is given by

$$y_j^{a_i} = x_j^{a_i}/x_i^{a_j}. \quad (1.1)$$

are called the orbifold charts on $\mathbb{P}(a_0, a_1, a_2, a_3)$.

$\mathbb{P}(a_0, a_1, a_2, a_3)$ has an index $a_i$ quotient singularity at $P_i$ and an index $(a_i, a_j)$ quotient singularity along the line $(x_k = x_\ell = 0)$.

For every $m \in \mathbb{Z}$ there is a rank 1 sheaf $\mathcal{O}_\mathbb{P}(m)$ which is locally free only if $a_i|m$ for every $i$. A basis of the space of sections of $\mathcal{O}_\mathbb{P}(m)$ is given by all monomials in $x_0, x_1, x_2, x_3$ with weighted degree $m$. Thus $\mathcal{O}_\mathbb{P}(m)$ may have no sections for some $m > 0$.

2. ANTI-CANONICALLY EMBEDDED QUASI SMOOTH SURFACES. Let $X \in |\mathcal{O}_\mathbb{P}(m)|$ be a surface of degree $m$. The adjunction formula

$$K_X \cong \mathcal{O}_\mathbb{P}(K_\mathbb{P} + X)|_X \cong \mathcal{O}_\mathbb{P}(m - (a_0 + a_1 + a_2 + a_3))|_X$$

holds iff $X$ does not contain any of the singular lines. If this condition holds then $X$ is a (singular) del Pezzo surface iff $m < a_0 + a_1 + a_2 + a_3$. It is also well understood that from many points of view the most interesting cases are when $m$ is as large as possible. Thus we consider the case $X_d \in |\mathcal{O}_\mathbb{P}(d)|$ for $d = a_0 + a_1 + a_2 + a_3 - 1$. We say that such an $X$ is anticanonically embedded.
Except for the classical cases

$$(a_0, a_1, a_2, a_3) = (1, 1, 1, 1), \ (1, 1, 1, 2) \ or \ (1, 1, 2, 3),$$

$X$ is not smooth and it passes through some of the vertices $P_i$. Thus the best one can hope is that $X$ is smooth in the orbifold sense, called quasi smooth. At the vertex $P_i$ this means that the preimage of $X$ in the orbifold chart $\mathbb{C}^3(y_j, y_k, y_\ell)$ is smooth. In terms of the equation of $X$ this is equivalent to saying that

(2.1) For every $i$ there is a $j$ and a monomial $x_i^{m_i}x_j$ of degree $d$.

Here we allow $j = i$, corresponding to the case when the general $X$ does not pass through $P_i$. The condition that $X$ does not contain any of the singular lines is equivalent to

(2.2) If $(a_i, a_j) > 1$ then there is a monomial $x_i^{b_i}x_j^{b_j}$ of degree $d$.

Finally, if every member of $|\mathcal{O}_p(d)|$ contains a coordinate axis ($x_k = x_\ell = 0$) then the general member should be smooth along it, except possibly at the vertices. That is

(2.3) For every $i, j$, either there is a monomial $x_i^{b_i}x_j^{b_j}$ of degree $d$, or there are monomials $x_i^{c_i}x_j^{c_j}x_k$ and $x_i^{d_i}x_j^{d_j}x_\ell$ of degree $d$.

The computer search done in connection with Demailly-Kollar ([DeKo]) looked at values of $a_i$ in a certain range to find the $a_i$ satisfying the constraints (2.1–2.3). This approach starts with the $a_i$ and views (2.1–2.3) as linear equations in the unknowns $m_i, b_i, c_i, d_i$. In order to find all solutions, we change the point of view.

3. DESCRIPTION OF THE COMPUTER PROGRAM. We consider (2.1) to be the main constraint, the $m_i$ as coefficients and the $a_i$ as unknowns. The corresponding equations can then be written as a linear system

$$(M + J + U)(a_0 a_1 a_2 a_3)^t = (-1 \ -1 \ -1 \ -1)^t$$

where $M = \text{diag}(m_0, m_1, m_2, m_3)$ is a diagonal matrix, $J$ is a matrix with all entries $-1$ and $U$ is a matrix where each row has 3 entries $= 0$ and one entry $= 1$. It is still not easy to decide when such a system has positive integral solutions, but the main advantage is that some of the $m_i$ can be bounded a priori.
Consider for instance $m_3$. The relevant equation is

$$m_3a_3 + a_j = a_0 + a_1 + a_2 + a_3 - 1.$$ 

Since $a_3$ is the biggest, we get right away that $1 \leq m_3 \leq 2$. Arguing inductively with some case analysis we obtain that

(3.2) $2 \leq m_2 \leq 4$ and $2 \leq m_1 \leq 10$,

(3.3) or the $a_i$ are in a series $(1, a, b, b, \ldots)$ with $a|2b - 1$. The latter satisfy (2.2) only for $a = b = 1$.

Thus we have only finitely many possibilities for the matrix $U$ and the numbers $m_1, m_2, m_3$. Fixing these values, we obtain a linear system

$$(M + J + U)(a_0 \begin{array}{c} a_1 \\ a_2 \\ a_3 \end{array})^t = \left( \begin{array}{ccc} -1 & -1 & -1 \\ -1 & -1 & -1 \end{array} \right)^t,$$

where the only variable coefficient is the upper left corner of $M$. Solving these formally we obtain that

$$a_0 = \frac{\gamma_0}{m_0\alpha + \beta},$$

where $\alpha, \beta, \gamma_0$ depend only on $U$ and $m_1, m_2, m_3$. $a_0$ is supposed to be a positive integer, thus if $\alpha \neq 0$ then there are only finitely many possibilities $m_0$. Once $m_0$ is also fixed, the whole system can be solved and we check if the $a_i$ are all positive integers. We get 1362 cases.

If $\alpha = 0$ but $\beta \neq 0$ then the general solution of the system has the form

$$a_0 = \frac{\gamma_0}{\beta}, a_i = \frac{m_0\delta_i + \gamma_i}{\beta} \text{ for } i = 1, 2, 3.$$ 

These generate the series of solutions, 405 of them. Finally, with some luck, the case $\alpha = \beta = \gamma_0 = 0$ never occurs, so we do not have to check further.

The resulting solutions need considerable cleaning up. Many solutions $a_0, a_1, a_2, a_3$ occur multiply and we also have to check the other conditions (2.2–2.3). At the end we get the complete list, given in Theorem 8.

The computer programs are available at

www.math.princeton.edu/\texttt{jmjohnso/LogDelPezzo}.

These log del Pezzo surfaces are quite interesting in their own right. Namely, it turns out that for many of them, members of the linear systems $|−mK_X|$ can not be very singular at any point. First we recall the notions log canonical etc. (see, for instance, Kollár-Mori ([KoMo], 2.3) for a detailed introduction).
DEFINITION 4. — Let $X$ be a surface and $D$ a $\mathbb{Q}$-divisor on $X$. Let $g : Y \to X$ be any proper birational morphism, $Y$ smooth. Then there is a unique $\mathbb{Q}$-divisor $D_Y = \sum e_iE_i$ on $Y$ such that

$$K_Y + D_Y \equiv g^*(K_X + D) \quad \text{and} \quad g_*D_Y = D.$$

We say that $(X, D)$ is canonical (resp. klt, resp. log canonical) if $e_i \geq 0$ (resp. $e_i > -1$, resp. $e_i \geq -1$) for every $g$ and for every $i$.

DEFINITION 5 (Keel-McKernan [KeMcK]). — Let $X$ be a normal surface. A tiger on $X$ is an effective $\mathbb{Q}$-divisor $D$ such that $D \equiv -K_X$ and $(X, D)$ is not klt. As illustrated in Keel-McKernan ([KeMcK]), the tigers carry important information about birational transformations of log del Pezzo surfaces.

REMARK 6. — By a result of Shokurov (cf. Keel-McKernan [KeMcK], 22.2), if the log del Pezzo surface $X$ has Picard number 1 and it has a tiger then $|\mathcal{O}_X(-mK_X)| \neq \emptyset$ for some $m = 1, 2, 3, 4, 6$. The log del Pezzo surfaces in Theorem 8 mostly have bigger Picard number. It is quite interesting though that the two results work for almost the same cases.

We use the following sufficient condition to obtain the existence of Kähler-Einstein metrics.

THEOREM 7 (Nadel [Na], Demailly-Kollar [DeKo]). — Let $X$ be an $n$ dimensional Fano variety (possibly with quotient singularities). Assume that there is an $\epsilon > 0$ such that

$$\left( X, \frac{n + \epsilon}{n + 1}D \right)$$

is klt

for every effective $\mathbb{Q}$-divisor $D \equiv -K_X$. Then $X$ has a Kähler-Einstein (or orbifold) metric. \hfill \Box

The main result of this note is the following.

THEOREM 8. — There is an anticanonically embedded quasi smooth log del Pezzo surface $X_d \subset \mathbb{P}(a_0, a_1, a_2, a_3)$ iff the $a_i$ and $d$ are among the following. The table below also gives our results on the nonexistence of tigers (Definition 5) and on the existence of Kähler-Einstein metrics. (Lower case $y$ means that the answer has been previously known.)
REMARK 9.— The above results hold for every quasi smooth surface with the indicated numerical data.

Near the end of the list there are very few monomials of the given degree and in many cases there is only one such surface up to isomorphism. In some other cases, for instance for the series, there are moduli.

It is generally believed that the algebraic geometry of any given log del Pezzo surface can be understood quite well. There is every reason to believe that all of the remaining cases of Theorem 8 can be decided, though it may require a few pages of computation for each of them.
10. HOW TO CHECK IF \((X, D)\) IS KLT OR NOT?. Definition 4 requires understanding all resolutions of singularities. Instead, we use the following multiplicity conditions to check that a given divisor is klt. These conditions are far from being necessary.

Let \(X\) be a surface with quotient singularities. Let the singular points be \(P_i \in X\) and we write these locally analytically as

\[
p_i : (\mathbb{C}^2, Q_i) \rightarrow (\mathbb{C}^2/G_i, P_i) \cong (X, P_i),
\]

where \(G_i \subset GL(2, \mathbb{C})\) is a finite subgroup. We may assume that the origin is an isolated fixed point of every nonidentity element of \(G_i\) (cf. Brieskorn [Br]). Let \(D\) be an effective \(\mathbb{Q}\)-divisor on \(X\). Then \((X, D)\) is klt if the following three conditions are satisfied:

(10.1) (Non isolated non-klt points) \(D\) does not contain an irreducible component with coefficient \(\geq 1\).

(10.2) (Canonical at smooth points) \(\text{mult}_P D \leq 1\) at every smooth point \(P \in X\). This follows from Kollár-Mori ([KoMo], 4.5).

(10.3) (Klt at singular points) \(\text{mult}_{Q_i} D_i \leq 1\) for every \(i\) where \(D_i := p_i^* D\).

This follows from Kollár-Mori ([KoMo], 5.20) and the previous case.

In our applications we rely on the following estimate.

**Proposition 11.** — Let \(Z \subset \mathbb{P}(a_0, \ldots, a_n)\) be a \(d\)-dimensional subvariety of a weighted projective space. Assume that \(Z\) is not contained in the singular locus and that \(a_0 \leq \cdots \leq a_n\). Let \(Z_i \subset \mathbb{A}^n\) denote the preimage of \(Z\) in the orbifold chart

\[
\mathbb{A}^n \rightarrow \mathbb{A}^n/\mathbb{Z}_{a_i} \cong \mathbb{P}(a_0, \ldots, a_n) \setminus \{x_i = 0\}.
\]

Then for every \(i\) and every \(p \in Z_i\),

\[
\text{mult}_p Z_i \leq (a_n \cdots a_{n-d})(Z \cdot \mathcal{O}(1)^d).
\]

Moreover, if \(Z \neq (x_0 = \cdots = x_{n-d-1} = 0)\) then we have a stronger inequality

\[
\text{mult}_p Z_i \leq (a_n \cdots a_{n-d+1}a_{n-d-1})(Z \cdot \mathcal{O}(1)^d).
\]

**Proof.** — Let \(0 \in C(Z) \subset \mathbb{A}^{n+1}\) denote the cone over \(Z\) with vertex 0. \(Z_i\) can be identified with the hyperplane section \(C(Z) \cap \{x_i = 1\}\). The multiplicity of a point is an upper semi continuous function on a variety, thus it is sufficient to prove that

\[
\text{mult}_0 C(Z) \leq (a_n \cdots a_{n-d})(Z \cdot \mathcal{O}(1)^d).
\]
This is proved by induction on dim $Z$.

If $C(Z)$ is not contained in the coordinate hyperplane ($x_i = 0$), then write

$$Z \cap (x_i = 0) = \sum \sum \sum \sum \sum m_j Y_j \subset \mathbb{P}(a_0, \ldots, a_n).$$

Next we claim that

$$\sum \sum \sum \sum m_j (Y_j \cdot \mathcal{O}(1)^{d-1}) = a_i (Z \cdot \mathcal{O}(1)^d)$$

and

$$\sum \sum \sum \sum m_j \text{mult}_0 C(Y_j) \geq \text{mult}_0 C(Z).$$

The first of these is the associativity of the intersection product, and the second is a consequence of the usual estimate for the intersection multiplicity (cf. Fulton [Fu], 12.4) applied to $C(Z), (x_i = 0)$ and $d - 1$ other general hyperplanes through the origin. (Note that in the first edition of Fulton ([Fu]) there is a misprint in (12.4). $\sum_{i=1}^{r} e_P(V_i)$ should be replaced by $\prod_{i=1}^{r} e_P(V_i)$.) By the inductive assumption $\text{mult}_0 C(Y_j) \leq (Y_j \cdot \mathcal{O}(1)^{d-1})$, hence $\text{mult}_0 C(Z) \leq (Z \cdot \mathcal{O}(1)^d)$ as claimed.

In most cases, we can even choose $i < n - d$. This is impossible only if $Z \subset (x_0 = \cdots = x_{n-d-1} = 0)$, but then equality holds. \qed

**Corollary 12.** — Let $X_d \subset \mathbb{P}(a_0, a_1, a_2, a_3)$ be a quasismooth surface of degree $d = a_0 + a_1 + a_2 + a_3 - 1$. Then $X$ does not have a tiger if $d \leq a_0 a_1$. If $(x_0 = x_1 = 0) \not\subset X$ then $d \leq a_0 a_2$ is also sufficient.

**Proof.** — Assume that $D \subset X_d$ is a tiger. We can view $D$ as a 1-cycle in $\mathbb{P}(a_0, a_1, a_2, a_3)$ whose degree is

$$(D \cdot \mathcal{O}_X(1)) = (\mathcal{O}_\mathbb{P}(d) \cdot \mathcal{O}_\mathbb{P}(1) \cdot \mathcal{O}_\mathbb{P}(1)) = \frac{d}{a_0 a_1 a_2 a_3}.$$  

By Proposition 11, this implies that the multiplicity of $D_i$ (as in (10.3)) is bounded from above by $\frac{d}{a_0 a_1}$ at any point. Thus $(X, D)$ is klt if $d \leq a_0 a_1$.

If $(x_0 = x_1 = 0) \not\subset X$ then we can weaken this to $d \leq a_0 a_2$, again by Proposition 11. \qed

Using Theorem 7 and a similar argument we obtain the following.

**Corollary 13.** — Let $X_d \subset \mathbb{P}(a_0, a_1, a_2, a_3)$ be a quasismooth surface of degree $d = a_0 + a_1 + a_2 + a_3 - 1$. Then $X$ admits a Kähler-Einstein metric if $d < \frac{3}{2} a_0 a_1$. If $(x_0 = x_1 = 0) \not\subset X$ then $d < \frac{3}{2} a_0 a_2$ is also sufficient.
14. Proof of Theorem 8. — The nonexistence of tigers and the existence of a Kähler-Einstein metric in the sporadic examples follows from Corollary 12 and Corollary 13. There are 5 cases when we need to use that $X$ does not contain the line $(x_0 = x_1 = 0)$. This is equivalent to claiming that the equation of $X$ contains a monomial involving $x_2, x_3$ only. In all 5 cases this is already forced by the condition (2.1).

Assume next that $X$ is one of the series $(2, 2k + 1, 2k + 1, 4k + 1)$. Its equation is a linear combination of terms

$$x_0^{4k+2}, x_3^2 x_0, x_3(x_1 + x_2)x_0^{k+1}, g_4(x_1, x_2), g_2(x_1, x_2)x_0^{2k+1}.$$ 

Moreover, the conditions (2.1–2.3) imply that the first 2 appear with nonzero coefficient and $g_4$ does not have multiple roots. $(x_0 = 0)$ intersects $X$ in a curve $C$ with equation

$$(q_{8k+4}(x_1, x_2) = 0) \subset \mathbb{P}^2(2k + 1, 2k + 1, 4k + 1),$$

isomorphic to

$$(q_4(x_1, x_2) = 0) \subset \mathbb{P}^2(1, 1, 4k + 1).$$

Thus $C$ has 4 irreducible components $C_1 + C_2 + C_3 + C_4$ meeting at $P_3 = (0 : 0 : 0 : 1)$. This shows that $\frac{1}{2}C$ is not klt at $P_3$ and $\frac{1}{2}C$ is a tiger on $X$.

Next we prove that for $k \geq 2$, $(X, D)$ is log canonical for every effective $\mathbb{Q}$-divisor $D \equiv -K_X$. For $k = 1$ we show that $(X, \frac{3}{8}D)$ is log canonical. These are stronger than needed in order to apply Theorem 7.

Consider the linear system $\mathcal{O}_P(2(2k + 1))$. This is the pull back of $\mathcal{O}(2(2k + 1))$ from the weighted projective plane $\mathbb{P}(2, 2k + 1, 2k + 1)$. The latter is isomorphic to $\mathbb{P}(2, 1, 1)$ which is the quadric cone in ordinary $\mathbb{P}^3$ and the linear system is the hyperplane sections, thus very ample. Hence for every smooth point $P \in X$ there is a divisor $F \in |\mathcal{O}_X(2(2k + 1))|$ passing through $P$ and not containing any of the irreducible components of $D$. So

$$\text{mult}_P D \leq (D \cdot F) = \frac{2(2k + 1)(8k + 4)}{2(2k + 1)^2(4k + 1)} = \frac{4}{4k + 1} < 1.$$ 

We are left to deal with the singular points of $X$. These are at $P_3 = (0 : 0 : 0 : 1)$ and at $P_a = (0 : a : 1 : 0)$ where $a$ is a root of $g_4(x_1, 1)$.

$P_3$ is the most interesting. Let $p_3 : (S \cong \mathbb{C}^2, Q_3) \to (X, P_3)$ be a local orbifold chart. Intersecting $p_3^* D$ with a general member of the linear system $|x_0^{2k+1}, x_1^2|$ we obtain that

$$\text{mult}_{Q_3} p_3^* D \leq \frac{4k + 1}{2} (D \cdot \mathcal{O}(2(2k + 1))) = 2.$$
This is too big to apply (10.3). Let \( \pi : S' \to S \) be the blow up of the origin with exceptional divisor \( E \). Then

\[
K_{S'} + \alpha E + \pi_*^{-1}(p_3^*D) \equiv \pi^*(K_S + p_3^*D),
\]

and \( \alpha \leq 1 \). Using Shokurov’s inversion of adjunction (see, for instance Kollár-Mori [KoMo], 5.50) \( (X, D) \) is log canonical at \( P_3 \) if \( \pi_*^{-1}(p_3^*D)|_E \) is a sum of points, all with coefficient \( \leq 1 \). In order to estimate these coefficients, we write \( D = D' + \sum a_iC_i \) where \( D' \) does not contain any of the \( C_i \).

We first compute that

\[
(C_i \cdot C_j) = \frac{1}{4k+1} \quad \text{if} \ i \neq j, \quad \text{and} \quad (C_i \cdot \mathcal{O}(1)) = \frac{1}{(2k+1)(4k+1)}.
\]

From this we obtain that

\[
(C_i \cdot C_i) = (C_i \cdot \mathcal{O}(1)) - \sum_{j \neq i} (C_i \cdot C_j) = \frac{-(6k+2)}{(2k+1)(4k+1)}.
\]

Note that

\[
\frac{1}{(2k+1)(4k+1)} = (C_i \cdot D) = a_i(C_i \cdot C_i) + (\sum_{j \neq i} a_j)(C_i \cdot C_{i+1}) + (C_i \cdot D').
\]

Multiplying by \((2k+1)(4k+1)\) and using that \( \sum a_i \leq \text{mult}_{Q_3} p_3^*D \leq 2 \) and \( (C_i \cdot D') \leq 2(D \cdot D) \) this becomes

\[1 \leq -(6k+2)a_i + (2 - a_i)(2k+1) + 4 \quad \text{which gives} \quad a_i \leq \frac{4k+5}{8k+3}.\]

Furthermore,

\[
\text{mult}_{Q_3} p_3^*D' \leq \frac{1}{4}(p_3^*D' \cdot \sum p_3^*C_i) \leq \frac{4k+1}{4}(D \cdot \mathcal{O}(2)) = \frac{1}{2k+1}.
\]

Thus we see that

\[
\pi_*^{-1}(p_3^*D)|_E = \sum a_i\pi_*^{-1}(p_3^*C_i)|_E + \pi_*^{-1}(p_3^*D')|_E
\]

is a sum of 4 distinct points with coefficient \( \leq \frac{4k+5}{8k+3} \) and another sum of points where the sum of the coefficients is \( \leq \frac{1}{2k+1} \). This implies that \( (X, D) \) is log canonical at \( P_3 \) for \( k \geq 2 \).

If \( k = 1 \) then our estimate does not show that \( (X, D) \) is log canonical. However, we still get that \( \pi_*^{-1}(p_3^*D')|_E \) is a sum of points with coefficients \( \leq \frac{9}{11} + \frac{1}{3} \). Thus \( (X, \frac{33}{38}D) \) is log canonical at \( P_3 \).

The points \( P_a \) are easier. Only one of the \( C_i \) passes through each of them, and the multiplicity of the pull back of \( D' \) is bounded by \( \frac{2k+1}{4}(D \cdot \mathcal{O}(2)) = \frac{1}{4k+1} \). This shows right away that \( (X, D) \) is klt at these points.
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