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ALGEBRAS OF DIFFERENTIABLE FUNCTIONS IN THE PLANE

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1. — Introduction.

We denote by C_0 the Banach space of all complex-valued continuous functions on the plane that are zero at infinity, supplied with the supremum norm ||.||; and by D the dense subspace of C_0 consisting of infinitely differentiable functions with compact support. \mathcal{Q} is the set of all differential operators of the form

(1.1)
$$\sum a_{m,n} \partial^{m+n} / \partial x^m \partial y^n,$$

where the $a_{m,n}$ are complex constants.

If A is (1.1) its formal adjoint $\mathbf{\tilde{A}}$ is the operator

$$\sum (-1)^{m+n} a_{m,n} \mathrm{d}^{m+n} / \mathrm{d} x^m \mathrm{d} y^n.$$

For f in C_0 , the statement « Af is in C_0 » will be interpreted in the sense of the theory of distributions; Af is defined to be the function h in C_0 (unique if it exists) satisfying

$$\int (\mathbf{\tilde{A}}g)f = \int hg, \qquad g \in \mathbf{D}.$$

For a subset α of \mathcal{D} , we define $C_0(\alpha)$ to be the space of all f in C_0 which are such that Af is in C_0 for all A in α . A subspace B of C_0 will be called *a space of differentiable functions* if B is

(1) Dedicated to Professor Charles Loewner on the occasion of his 70 th birthday.

 $C_0(\alpha)$ for some subset α of 2. Each space of differentiable functions is translation-invariant; those that are furthermore invariant under rotations of the plane will be called *rotating* spaces of differentiable functions.

Certain of these spaces are familiar, namely the spaces C_0^N consisting of those functions in C_0 that have all derivatives of order $\leq N$ in C_0 , and the space C_0^∞ , which is $\cap C_0^N$. A rotating space of differentiable functions will be called *proper* if it is not C_0^∞ and not one of the C_0^N .

The main result of this paper is Theorem 1.1, which classifies the rotating spaces. A somewhat surprising consequence of the classification is Corollary 1.2, which observes that rotating spaces are automatically closed under pointwise multiplication.

We use the standard notations,

$$\frac{\partial}{\partial z} = \frac{1}{2} \left(\frac{\partial}{\partial x} - i \frac{\partial}{\partial y} \right),$$
$$\frac{\partial}{\partial \overline{z}} = \frac{1}{2} \left(\frac{\partial}{\partial x} + i \frac{\partial}{\partial y} \right).$$

THEOREM 1.1. — If α is a proper subset of

(1.2)
$$\{\partial^{m+n}/\partial z^n \partial \bar{z}^m : m+n=\mathbf{N}\} = \mathfrak{R}_{\mathbf{N}}$$

for N a positive integer, then $C_0(\alpha)$ is a proper rotating space of differentiable functions between C_0^N and C_0^{N-1} . If α_1 and α_2 are distinct proper subsets of (1.2), then $C_0(\alpha_1)$ and $C_0(\alpha_2)$ are distinct. Each proper rotating space of differentiable functions lies between some adjacent pair of improper rotating spaces C_0^N and C_0^{N-1} , and is a $C_0(\alpha)$ for some proper subset α of \Re_N .

COROLLARY 1.2. — Let B be a rotating space of differentiable functions. Then B is an algebra of functions, and B is a Banach algebra unless B is C_0^{∞} .

Theorem 1.1 is proved in section 5, and Corollary 1.2 in section 6. The first three sections are devoted to preliminary material; in sections 2 and 3 we establish the basic properties of spaces of differentiable functions, and in section 4 we classify the spaces of differentiable functions between C_0^N and C_0^{N-1} .

Our work is based on the existence and non-existence of certain supnorm estimates for constant-coefficient differential operators. These results appear in [2]; in section 7 we state the results from that paper, together with certain of their consequences, that will be used here.

An announcement of the results of this paper has appeared in [1]. In a subsequent paper [3] we shall study the analogues of rotating spaces of differentiable functions on Riemann surfaces.

2. — Properties of spaces of differentiable functions.

For a subset α of \mathcal{D} , we shall consider $C_0(\alpha)$ to be a topological linear space under the topology given by the semi-norms

 $f \rightarrow ||f||$

and

$$f \rightarrow ||\mathbf{A}f||, \qquad \mathbf{A} \in \boldsymbol{\alpha}.$$

Since \mathfrak{D} is countable-dimensional, the topology can be given by a countable number of semi-norms and is thus metrizable. If \mathfrak{a} is finite dimensional, $C_0(\mathfrak{a})$ is normable.

PROPOSITION 2.1. — The topological linear space $C_0(\alpha)$ is complete.

Proof. — Let $\{f_n\}$ be a Cauchy sequence in $C_0(\alpha)$. Then in particular there is a function f in C_0 with $f_n \to f$ uniformly. Let $A \in \alpha$. $\{Af_n\}$ is uniformly Cauchy so there is a function hin C_0 with $Af_n \to h$ uniformly. It suffices to show that Af = h. But A is continuous in the distribution topology, and in that topology $f_n \to f$, $Af_n \to h$. This proves Proposition 2.1.

 $C_0(\alpha)$ is metrizable, so by Proposition 2.1 is a Frechet space, and even a Banach space if α is finite dimensional. In particular, the closed graph theorem is applicable to $C_0(\alpha)$.

Suppose now that B is a space of differentiable functions, $B = C_0(\alpha_1)$ and $B = C_0(\alpha_2)$. The topologies we have given $C_0(\alpha_1)$ and $C_0(\alpha_2)$ are both stronger than pointwise convergence, so by the closed graph theorem, they must be the same. Thus we may speak of *the topology of* B without reference to any α for which $B = C_0(\alpha)$. This topology will be denoted by $\tau(B)$.

 $\mathbf{5}$

PROPOSITION 2.2. — Let B be a space of differentiable functions. Then D is dense in B.

Proof. — Let $B = C_0(\alpha)$. We may assume the identity operator in α . Let $f \in B$, $\varepsilon > 0$ and A_1, \ldots, A_n in α . We must find a function g in D with

$$||\mathbf{A}_i g - \mathbf{A}_i f|| < \varepsilon, \quad i = 1, \ldots, n.$$

Choose m in D, positive, $\int m = 1$, with support so close to 0 that

(2.1)
$$||m*(\mathbf{A}_i f) - \mathbf{A}_i f|| < \varepsilon, \quad i = 1, \ldots, n,$$

where * is convolution. If h = m * f, then h is infinitely differentiable, it and all of its derivatives vanish at infinity, and (2.1) becomes

$$||\mathbf{A}_i h - \mathbf{A}_i f|| < \varepsilon, \quad i = 1, \ldots, n.$$

Now let k be a function in D, identically 1 near 0. For r > 0 define k, by

$$k_r(x, y) = k\left(\frac{x}{r}, \frac{y}{r}\right)$$

Then as $r \to \infty$, each derivative of $k_r h$ converges uniformly to the corresponding derivative of h, so we may take $g = k_r h$ for r sufficiently large.

PROPOSITION 2.3. — Let B_1 and B_2 be spaces of differentiable functions. Then the following are equivalent:

1º $B_1 \subset B_2$;

2° Restricted to D, the topology $\tau(B_1)$ is stronger than the topology $\tau(B_2)$.

Proof. — (1° implies 2°). By the closed graph theorem, the injection $B_1 \rightarrow B_2$ is continuous.

(2° implies 1°). The identity map, from D in $\tau(B_1)$ to D in $\tau(B_2)$, being continuous, extends to the completions, which are B_1 and B_2 by Propositions 2.1 and 2.2. The resulting map is clearly the injection of B_1 into B_2 . Hence Proposition 2.3 is proved.

Suppose that $B_1 = C_0(\alpha_1)$ and $B_2 = C_0(\alpha_2)$. Then 2° in the above can be rephrased as follows. For each A in α_2 there are A_1, \ldots, A_n in α_1 so that

$$(2.2) \quad ||\mathbf{A}g|| \leqslant \mathbf{K}(||g|| + ||\mathbf{A}_{\mathbf{1}}g|| + \cdots + ||\mathbf{A}_{n}g||), \qquad g \in \mathbf{D}.$$

Thus problems of classification of space of differentiable functions are more or less equivalent to questions of the existence of estimates of the form (2.2). The results that we shall need concerning such estimates are given in section 7.

Each space of differentiable functions is a $C_0(\alpha)$ for many α . It is convenient to have a notation for the largest such α . If B is a space of differentiable functions, we shall denote by α_B the subspace of \mathcal{Q} consisting of all A for which Af is in C_0 , all f in B. Clearly $B = C_0(\alpha_B)$; and any other α satisfying $B = C_0(\alpha)$ must be a subset of α_B . Note that B is a rotating space of differentiable functions if and only if α_B is rotation invariant.

PROPOSITION 2.4. — Let B be a space of differentiable functions. Then the following are equivalent:

1º B is a Banach space;

2º For some N, $C_0^N \subset B$;

3° $\alpha_{\rm B}$ is a finite-dimensional subspace of 2.

Proof. — (3° implies 1°) Clear since $B = C_0(\alpha_B)$.

(1° implies 2°) Let $||.||_B$ be a norm for B. The injection $C_0^{\infty} \rightarrow B$ is continuous by the closed graph theorem. Thus, by the definition of the topology of C_0^{∞} , there is a finite subset α of \mathfrak{Q} and a constant K so that

$$||g||_{\mathsf{B}} \leqslant \mathsf{K}(||g|| + \sum_{\mathsf{A} \in \mathcal{A}} ||\mathsf{A}g||), \quad g \in \mathsf{D}.$$

It then follows from Proposition 2.3 that B contains $C_0(\alpha)$ and thus B contains C_0^N if N exceeds the order of all the operators in α .

(2° implies 3°) If α_B is not finite-dimensional, it contains operators of arbitrarily high order. By Corollary 7.2 this cannot occur if B contains C_0° for some N.

3. - Properties of rotating spaces of differentiable functions.

In what follows we shall denote by \mathcal{Q}_N the subspace of \mathcal{Q} consisting of those differential operators of order $\leq N$.

It will be convenient to have a notation for rotation of functions and operators in the plane. Let ω be a complex number of modulus 1. For f in C_0 , we denote by $R_{\omega}f$ the function defined by $R_{\omega}f(z) = f(\omega z)$. For A in 2, $R_{\omega}A$ is defined to be the operator in 2 satisfying

$$(\mathbf{R}_{\boldsymbol{w}}\mathbf{A})(g) = \mathbf{A}(\mathbf{R}_{\boldsymbol{w}}g), \qquad g \in \mathbf{D}.$$

Note that

(3.1)
$$\mathbf{R}_{\omega}(\partial^{m+n}/\partial z^m \partial \bar{z}^n) = \mathscr{W}^{m-n} \partial^{m+n}/\partial z^m \partial \bar{z}^n.$$

LEMMA 3.1. — Let A be an operator in \mathcal{D} , s an integer. Then the following are equivalent:

1º $R_w A = w^s A$ for all w with |w| = 1;

2º A is a linear combination of the $\partial^{m+n}/\partial z^m \partial \overline{z}^n$ with m - n = s.

Proof. — $(2^{\circ} \text{ implies } 1^{\circ})$ This is immediate from (3.1.)

(1° implies 2°) Let M be a non-negative integer, A_M the homogeneous part of A of degree M. As a consequence of 1°, and since rotation preserves homogeneous parts,

$$\mathbf{R}_{\mathbf{w}}\mathbf{A}_{\mathbf{M}} = \mathbf{w}^{s}\mathbf{A}_{\mathbf{M}}, \qquad |\mathbf{w}| = 1.$$

But A_M is of the form

$$\sum_{n+n=M} a_{m,n} \partial^{m+n} / \partial z^m \partial \bar{z}^n,$$

so because of (3.1), the equality (3.2) cannot hold unless $a_{m,n} = 0$ for $m - n \neq s$. This proves Lemma 3.1.

The operators A in 2 satisfying the conditions of Lemma 3.1 for some integer s will be called *rotating operators*.

Now let B be a rotating space of differentiable functions, so that α_B , is a rotation-invariant subspace of \mathcal{D} . We want to show that α_B is spanned by the rotating operators it contains. We need the following well known result.

PROPOSITION 3.2. — Let G be a commutative compact group and $\sigma \rightarrow U_{\sigma}$ a continuous representation of G on a finite dimensional complex linear space V. Then V is spanned by common eigenvectors; i.e., there is a basis v_1, \ldots, v_n of V and characters $\gamma_1, \ldots, \gamma_n$ of G so that

 $U_{\sigma}v_i = \gamma_i(\sigma)v_i, \quad \sigma \in G, \quad i = 1, \ldots, n.$

Let N be a positive integer. Then $\alpha_B \cap \mathcal{Q}_N$ is a finitedimensional rotation-invariant subspace of \mathcal{Q} . Proposition 3.2 applied to the representation $\omega \to R_{\omega}$ of the circle group $\{\omega : |\omega| = 1\}$ on $\alpha_B \cap \mathcal{Q}_N$ yields the following.

COROLLARY 3.3. — Let B be a rotating space of differentiable functions. Then $\alpha_B \cap \mathfrak{Q}_N$ has a basis of rotating operators.

Let us first consider the case when α_B is not finite-dimensional. Then by Corollary 3.3, α_B must contain rotating operators of arbitrarily high order. As a consequence of Corollary 7.6 below, α_B contains each \mathcal{Q}_N and thus all of \mathcal{Q} . So we have proved.

PROPOSITION 3.4. — The only rotating space of differentiable functions B having $\alpha_{\rm B}$ infinite-dimensional is the space C_0^{∞} .

So now let B be a rotating space of differentiable functions having α_B finite-dimensional. Let N be the largest integer so that α_B contains an operator of order N. By Corollary 3.3. $\alpha_B = \alpha_B \cap 2_N$ must contain a rotating operator of order N. Thus, by Corollary 7.6, α_B contains 2_{N-1} , and as a consequence each function in B has all derivatives of order < N in C₀. We have proved.

PROPOSITION 3.5. — Let B be a rotating space of differentiable functions that is not C_0^{∞} . Then there is a positive integer N so that

$$C_0^N \subset B \subset C_0^{N-1}$$
.

4. — Spaces between C_0^N and C_0^{N-1} .

In view of Proposition 3.5, to complete the classification of rotating spaces of differentiable functions, it remains only to study those between C_0^N and C_0^{N-1} . In this section we obtain a classification of all of the spaces (not only the rotating ones) between C_0^N and C_0^{N-1} . The next lemma provides the main

tool by showing that when B is such a space, then α_B contains none but the expected operators. (And we note in passing that a general space B, not contained between adjacent C_0^N and C_0^{N-1} , is intractable precisely because its α_B is not easy to describe).

LEMMA 4.1. — Let $B = C_0(\alpha)$ be a space of differentiable functions satisfying $C_0^N \subset B \subset C_0^{N-1}$. Then α_B is the linear subspace of Ω spanned by α and Ω_{N-1} .

Proof. — Let $A \in \alpha_B$. $f \to Af(0)$ is a continuous linear functional on $B = C_0(\alpha_B)$, and thus, since $B = C_0(\alpha)$, there are A_1, \ldots, A_n in α so that

$$|\mathbf{A}g(0)| \leqslant \mathbf{K}(||\mathbf{A}_1g|| + \cdots + ||\mathbf{A}_ng||), \qquad g \in \mathbf{D}.$$

Since $C_0^N \,\subset \, C_0(\alpha)$, the A_i are of order $\leq N$ by Corollary 7.2. Because of Theorem 7.1 below, A is of order $\leq N$, and the homogeneous part of A of order N is a linear combination of the corresponding homogeneous parts of the A_i . Thus A is in the linear subspace of \mathcal{Q} spanned by α and \mathcal{Q}_{N-1} . Since it is clear that the linear subspace of \mathcal{Q} spanned by α and Q_{N-1} is contained in α_B , the proof of Lemma 4.1 is complete.

THEOREM 4.2. — Let N be a positive integer. Then the mapping

$$(4.1) \qquad \qquad \alpha \to C_0(\alpha)$$

establishes a one-one correspondence between the linear subspaces α of $\mathfrak D$ satisfying

and those spaces B of differentiable functions satisfying

(4.3)
$$C_0^{\mathsf{N}} \subset \mathbf{B} \subset C_0^{\mathsf{N}-1}.$$

The inverse of the mapping (4.1) is

$$(4.4) B \to \alpha_{B}.$$

Proof. — That $C_0^N \subset C_0(\alpha) \subset C_0^{N-1}$ if α satisfies (4.2) is clear. Let B be any space of differentiable functions satisfying (4.3). Since $B = C_0(\alpha_B)$, to show the mapping (4.1) is onto, it

is only necessary to show that $\mathcal{Q}_{N-1} \subset \alpha_B \subset \mathcal{Q}_N$. That $\mathcal{Q}_{N-1} \subset \alpha_B$ is clear, and $\alpha_B \subset \mathcal{Q}_N$ follows from Corollary 7.2 below. Finally, for any linear subspace α of \mathcal{Q} satisfying (4.2), $\alpha = \alpha_{C_0(\alpha)}$, by Lemma 4.1, so the mapping (4.1) is one-one and has (4.4) for its inverse as claimed.

The above proof of Theorem 4.2 actually shows somewhat more. We shall denote by C_{κ} the subspace of C_0 consisting of those functions having compact support. If B_1 and B_2 are distinct spaces of differentiable functions, it is still possible that they are the same locally; i.e., that $B_1 \cap C_{\kappa} = B_2 \cap C_{\kappa}$. This is the case, for instance, when $B_1 = C_0(\partial^2/\partial x \partial y, \partial/\partial x)$ and $B_2 = C_0(\partial^2/\partial x \partial y)$. Indeed, let D_{ϵ} resp. $C_{\epsilon}(\partial^2/\partial x \partial y)$ consist of the functions in D resp. $C_0(\partial^2/\partial x \partial y)$ having support in the ball of radius $1/\epsilon$. Then the closure of D_{ϵ} in $C_0(\partial^2/\partial x \partial y)$ contains at least $C_{2\epsilon}(\partial^2/\partial x \partial y)$. Hence we need only compare the norms of $C_0(\partial^2/\partial x \partial y)$ and $C_0(\partial^2/\partial x \partial y, \partial/\partial x)$ on each fixed D_{ϵ} . And then it is evident that

$$\left|\frac{\partial f}{\partial x}(a, b)\right| \leqslant \int_{-1/\varepsilon}^{b} \left|\frac{\partial^2 f}{\partial x \partial y}\right| dy \leqslant \frac{2}{\varepsilon} \sup \left|\frac{\partial^2 f}{\partial x \partial y}\right|.$$

The following proposition shows, however, that such collapsing of norms can not occur on the spaces we are studying in this paper.

PROPOSITION 4.3. — Let B_1 and B_2 be distinct spaces of differentiable functions between C_0^N and C_0^{N-1} . Then $B_1 \cap C_K$ and $B_2 \cap C_K$ are distinct.

Proof. — Assume that
$$B_1 \cap C_K = B_2 \cap C_K$$
. Let

$$E_j = \{f : f \in B_j, f(z) = 0 \text{ if } |z| \ge 1\}, \quad j = 1, 2.$$

Then $E_1 = E_2$. E_j is a closed linear subspace of the Banach space B_j and is thus a Banach space in the induced topology. By the closed graph theorem, the B_1 topology on $E_1 = E_2$ is identical with the B_2 topology. Since $B_1 \neq B_2$, then $\alpha_{B_i} \neq \alpha_{B_i}$. We may assume that there is an operator A in α_{B_i} that is not in α_{B_i} . The mapping

$$f \to Af(0), \qquad f \in E_1 = E_2,$$

is a continuous linear functional, and thus there are A_1, \ldots, A_n

in $\alpha_{B_{\epsilon}}$ and a constant M so that

 $|\mathbf{A}g(0)| \leqslant \mathbf{M}(||\mathbf{A}_1g|| + \cdots + ||\mathbf{A}_ng||)$

for all g in D with g(z) = 0 for $|z| \ge 1$. Thus by Theorem 7.1, the homogeneous part of A of degree N is a linear combination of the corresponding homogeneous parts of the A_i. But since α_{B_i} is a linear subspace of \mathcal{D} containing \mathcal{D}_{N-1} , A is in α_{B_i} . Contradiction.

5. — Classification of rotating spaces.

This section is devoted to the proof of Theorem 1.1, which classifies the rotating spaces of differentiable functions.

There are three things to be established :

1° If α is a proper subset of \Re_N , then $C_0(\alpha)$ is a proper rotating space of differentiable functions between C_0^N and C_0^{N-1} .

2° If α_1 and α_2 are distinct proper subsets of \Re_N , then $C_0(\alpha_1)$ and $C_0(\alpha_2)$ are distinct.

3° If B is a proper rotating space of differentiable functions, then $B = C_0(\alpha)$, where α is a proper subset of \Re_N for some N.

Proof of 1°. — Let α be a proper subset of \Re_N . Since α spans a rotation-invariant subspace of \mathfrak{Q} , $C_0(\alpha)$ is a rotating space of differentiable functions. By Corollary 7.5, $C_0(\alpha) \in C_0^{N-1}$. And by Corollary 7.2, $C_0(\alpha) \neq C_0^{N-1}$. That $C_0^N \in C_0(\alpha)$ is clear. Since $C_0^N \subset C_0(\alpha) \subset C_0^{N-1}$, by Lemma 4.1, $\alpha_{C_0(\alpha)}$ is the linear subspace of \mathfrak{Q} spanned by α and \mathfrak{Q}_{N-1} and is thus not all of \mathfrak{Q}_N , so $C_0(\alpha) \neq C_0^N$.

Proof of 2°. — Let α be a proper subset of (1.2). We know that $C_0^N \subset C_0(\alpha) \subset C_0^{N-1}$, so by Lemma 4.1, $\alpha_{C_0(\alpha)}$ is the linear subspace of \mathfrak{D} spanned by α and \mathfrak{D}_{N-1} . Thus if α_1 and α_2 are distinct proper subsets of \mathfrak{R}_N , $\alpha_{C_0(\alpha_1)}$ and $\alpha_{C_0(\alpha_1)}$ are distinct, so $C_0(\alpha_1)$ and $C_0(\alpha_2)$ must be distinct.

Proof of 3°. — Let B be a proper rotating space of differentiable functions. Then by Proposition 3.5, there is a positive integer N so that $C_0^N \subset B \subset C_0^{N-1}$. Let α be the intersection of \Re_N and α_B . We will show that α is a proper subset of \Re_N and $B = C_0(\alpha)$. First it is necessary to relate α and α_B .

Let α' be the linear subspace of \mathfrak{D} spanned by α and \mathfrak{D}_{N-1} . We will show $\alpha' = \alpha_B$. First, $\alpha \subset \alpha_B$, and $\mathcal{Q}_{N-1} \subset \alpha_B$ since $B \subset C_0^{N-1}$, so $\alpha' \subset \alpha_B$. We have to demonstrate the reverse inclusion. By Corollary 3.2, $\alpha_{\rm B}$ has a basis of rotating operators. Let A be one. This A is of order $\leq N$, for if not, by Corollary 7.2, $B = C_0(\alpha_B)$ would not contain C_0^N . Let $A = A_1 + A_2$, where order $A_1 = N$, order $A_2 < N$. Since $\mathfrak{Q}_{n-1} \subset \mathfrak{A}_{B}, A_{2} \in \mathfrak{A}_{B}$, so $A_{1} \in \mathfrak{A}_{B}$. But A_{1} is a constant multiple of some operator in α , so $A \in \alpha'$. This shows that $\alpha_B \subset \alpha'$, which completes the proof that $\alpha_B = \alpha'$. α is not all of \Re_N since $B \neq C_0^{N-1}$. There must be some operator of order N in α_{B} , for otherwise we would have $\alpha_{B} \subset \mathcal{Q}_{N-1}$; and thus $B = C_0(\alpha_B) \supset C_0(\mathcal{Q}_{N-1}) = C_0^{N-1}$. Thus, since $\alpha_B = \alpha'$, α is non-empty. So we know α to be a proper subset of \Re_N and it remains to show $B = C_0(\alpha)$. Part 1° of the proof shows that $C_0^N \subset C_0(\alpha) \subset C_0^{N-1}$, so by Lemma 4.1, $\alpha_{C_0(\alpha)} = \alpha'$. But $\alpha' = \alpha_{\mathbf{B}}$, so $\mathbf{B} = C_0(\alpha_{\mathbf{B}}) = C_0(\alpha') = C_0(\alpha_{\mathbf{G},(\alpha)}) = C_0(\alpha)$. This completes the proof of Theorem 1.1.

6. — Rotating spaces as algebras.

In this section we show that the rotating spaces of differentiable functions are all algebras (and that all except C_0^{∞} are Banach algebras). Because of Proposition 3.5 it is enough to show that each space of differentiable functions between C_0^{∞} and $C_0^{\infty-1}$ is a Banach algebra.

LEMMA 6.1. — Let A be an operator in \mathcal{Q} of order N. Then there are A'_k and A''_k in \mathcal{Q} of order < N so that

$$Afg = fAg + gAf + \sum_{k} A'_{k}fA''_{k}g$$
 for all $f, g \in D$.

Proof. — It suffices to prove the assertion for $A = \partial^{m+n}/\partial x^m \partial y^n$. The result is true for m + n = 1. And it is simple to establish the induction step: If the assertion is valid for $\partial^{m+n}/\partial x^m \partial y^n$, then it is valid for $\partial^{m+n+1}/\partial x^{m+1} \partial y^n$ and $\partial^{m+n+1}/\partial x^m \partial y^{n+1}$.

LEMMA 6.2. — Let B be a space of differentiable functions between C_0^N and C_0^{N-1} . Let $A \in \alpha_B$. Then there are A'_k and A''_k

in \mathfrak{D} of order less than the order of A so that, for all f and g in B, the distribution Afg is equal to the continuous function

$$fAg + gAf + \sum_{k} A'_{k}fA''_{k}g.$$

Proof. — We use the A'_k and A''_k given by Lemma 6.1. We shall prove that

(6.1)
$$\int (fAg + gAf + \sum_{k} A'_{k}fA''_{k}g)h = \int fg\tilde{A}h, \quad h \in \mathbb{D},$$

for all f and g in B. Once (1.1) is established, by the definition of the distribution Lfg, we are done. Fix h in D. By the choice of the L'_{κ} and L''_{κ} , (6.1) holds for f and g in D. D \times D is dense in B \times B by Proposition 2.2. Both sides if (6.1) are continuous in (f, g) in the topology of B \times B, so (6.1) holds for all f and g in B.

PROPOSITION 6.3. — Let B be a space of differentiable functions between C_0^N and C_0^{N-1} . Then B is a Banach algebra.

Proof. — By Lemma 6.2, B is an algebra. Let α be a basis for α_B . Define the norm $||\cdot||_B$ on B by

$$||f||_{\mathrm{B}} = \sum_{\mathrm{A} \in \mathcal{A}} ||\mathrm{A}f||, \quad f \in \mathrm{B}.$$

Then $||\cdot||_{B}$ gives the topology of B, and it is clear, because of Lemma 6.2, that there is a constant K so that

$$||fg||_{\mathsf{B}} \leqslant \mathsf{K}||f||_{\mathsf{B}} ||g||_{\mathsf{B}}, \qquad f, \ g \in \mathsf{B}.$$

This completes the proof of Proposition 6.3.

Corollary 1.2. now follows immediately from Proposition 6.3 and Proposition 3.5.

7. — Sup norm estimates.

In this section we give the results concerning sup norm estimates on which our work is based.

The first theorem is a strengthening of Propositions 1 and 2 of [2].

THEOREM 7.1. — Let A_1, \ldots, A_m be operators in 2 of order $\leq N$. Let A be an operator in 2 for which there is a constant K so that

$$(7.1) |\mathbf{A}g(0)| \leqslant \mathbf{K}(||\mathbf{A}_1g|| + \cdots + ||\mathbf{A}_mg||)$$

for all g in D with support in $\{z : |z| < 1\}$. Then A has order $\leq N$ and the homogeneous part of A of order N is a linear combination of the corresponding homogeneous parts of A_1, \ldots, A_m .

Proof. — We denote by D_1 the subspace of D consisting of those g in D with support in $\{z:|z| < 1\}$. Take D_1 as domain for each of the A_k and by the mapping $g \rightarrow (A_1g, \ldots, A_mg)$ embed their joint range in the direct sum $\oplus {}^mC_0$ of m copies of C_0 . Because of (7.1), the functional

$$(\mathbf{A_1}g, \ldots, \mathbf{A_m}g) \rightarrow \mathbf{A}g(0)$$

on the embedded joint range is continuous with respect to the natural topology of $\oplus {}^{m}C_{0}$. By Hahn-Banach this functional extends to the whole space $\oplus {}^{m}C_{0}$. And by the Riesz representation we can write

(7.2)
$$Ag(0) = \sum_{k} \int A_{k}gd\mu_{k}, \qquad g \in D_{1},$$

for some measures μ_1, \ldots, μ_m of finite total mass. Write A and the A_k as sums of their homogeneous parts

$$A = \sum_{e} A^{e}, \qquad A_{k} = \sum_{e} A_{k}^{e}.$$

Substituting into (7.2) we have

(7.3)
$$\sum_{e} \mathbf{A}^{e} g(0) = \sum_{e} \sum_{k} \int \mathbf{A}^{e}_{k} g d\mu_{k}, \qquad g \in \mathbf{D}_{1}.$$

For r > 1 and g in D₁ define g_r in D₁ by

$$g_r(x, y) = g(rx, ry).$$

Then we have

 $A^{\epsilon}(g_r) = r^{\epsilon}(A^{\epsilon}g)_r, \qquad A^{\epsilon}_k(g_r) = r^{\epsilon}(A^{\epsilon}_kg)_r, \qquad g \in \mathbf{D}_1,$ so by (7.3),

(7.4)
$$\sum_{e} r^{e} \mathbf{A}^{e} g(0) = \sum_{e} \int r^{e} (\mathbf{A}_{k}^{e} g)_{r} d\mu_{k}, \quad g \in \mathbf{D}_{1}.$$

Let $M = \max \{N, \text{ degree } A\}$. Dividing (7.4) by r^{M} and letting $r \to \infty$, we have

(7.5)
$$A^{\mathsf{M}}g(0) = \sum_{k} c_{k} A^{\mathsf{M}}_{k}g(0), \qquad g \in \mathbf{D}_{1},$$

where c_k is the measure assigned to the origin by μ_k . If M > N, (7.5) is impossible, since each of the A_k^{M} is zero. Thus M = N, so

$$\mathbf{A}^{\mathbf{N}} = \sum_{\mathbf{k}} c_{\mathbf{k}} \mathbf{A}_{\mathbf{k}}^{\mathbf{N}}$$

is a consequence of (7.5).

COROLLARY 7.2. — Let A be an operator in \mathfrak{D} of order N. Then there exists an f in \mathbb{C}_0^{N-1} with Af not in \mathbb{C}_0 .

Proof. — Suppose that this were not the case. Then we would have $C_0^{N-1} \subset C_0(\{A\})$. By the closed graph theorem, the injection $C_0^{N-1} \rightarrow C_0(\{A\})$ is continuous. Thus, by the definition of the topology of C_0^{N-1} , there must be A_1, \ldots, A_m in \mathfrak{Q} of order $\leqslant N - 1$ and a constant K so that

$$|\mathbf{A}g|| \leqslant \mathbf{K}(||\mathbf{A}_1g|| + \cdots + ||\mathbf{A}_mg||), \qquad g \in \mathbf{D}.$$

Since A is of order N, this is impossible by Theorem 7.1.

The next result is half of Proposition 5 of [2].

THEOREM 7.3. — Let A be an elliptic operator in \mathfrak{Q} of order N. If A_0 is an operator in \mathfrak{Q} of order < N, then there is a constant K so that

$$||\mathbf{A}_{\mathbf{0}}g|| \leqslant \mathbf{K}(||\mathbf{A}g|| + ||g||), \quad g \in \mathbf{D}.$$

COROLLARY 7.4. — Let A be an elliptic operator in \mathcal{Q} of order N. Then $C_0(\{A\}) \subset C_0^{N-1}$.

Proof. — By Theorem 7.3, for every A_0 in 2 of order < N, there is a constant K so that

$$||\mathbf{A}_{\mathbf{0}}g|| \leqslant \mathbf{K}(||\mathbf{A}g|| + ||g||), \qquad g \in \mathbf{D}.$$

Thus, by Proposition 2.3, $C_0(\{A\})$ is contained in C_0^{N-1} .

COROLLARY 7.5. — Let $A = \delta^{m+n}/\delta z^m \delta \overline{z}^n$. Then $C_0(\{A\}) \subset C_0^{m+n-1}$

Proof. — A is elliptic, so Corollary 7.4 is applicable.

COROLLARY 7.6. — Let B be a space of differentiable functions. If $\alpha_{\rm B}$ contains a rotating operator A of order N, then $\alpha_{\rm B}$ contains 2_{N-1} .

Proof. - Since A is rotating of order N, its homogeneous part of order N must be a multiple of some $\partial^{m+n}/\partial z^m \partial \bar{z}^n$, for m + n = N. Thus A is elliptic, so by Corollary 7.4,

$$C_0(\{A\}) \subset C_0^{N-1}$$

But $B = C_0(\alpha_B) \subset C_0(\{A\})$ since $A \in \alpha_B$, so $B \subset C_0^{N-1}$. Equivalently, $\mathfrak{Q}_{N-1} \subset \mathfrak{A}_B$.

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