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# THE SYMPLECTIC KADOMTSEV-PETVIASHVILI HIERARCHY AND RATIONAL SOLUTIONS OF PAINLEVÉ VI 

by Henrik ARATYN \& Johan van de LEUR

## 1. Isomonodromic deformation problem, Painlevé VI equation and the Euler top equations.

Consider a Fuchsian system of linear differential equation with rational coefficients:

$$
\begin{equation*}
\frac{\partial}{\partial z} X(a, z)=-\sum_{i=1}^{3} \frac{A_{i}}{z-a_{i}} X(a, z), \quad \frac{\partial}{\partial a_{i}} X(a, z)=\frac{A_{i}}{z-a_{i}} X(a, z) \tag{1.1}
\end{equation*}
$$

The three-dimensional Schlesinger equations

$$
\begin{equation*}
\frac{\partial}{\partial a_{i}} A_{i}=\sum_{j=1, j \neq i}^{3} \frac{\left[A_{i}, A_{j}\right]}{a_{i}-a_{j}}, \quad \frac{\partial}{\partial a_{j}} A_{i}=\frac{\left[A_{i}, A_{j}\right]}{a_{j}-a_{i}}, \quad i \neq j . \tag{1.2}
\end{equation*}
$$

emerge as compatibility equations of the system (1.1) and describe monodromy preserving deformations for the linear differential equations in the complex plane.

Let us fix $a_{1}=0, a_{2}=1$ and $a_{3}=x$ and work with $2 \times 2$ matrices $A_{0}, A_{1}, A_{x}$. The Schlesinger equations reduce to:

$$
\dot{A}_{0}=-\frac{1}{x}\left[A_{0}, A_{x}\right], \quad \dot{A}_{1}=\frac{1}{1-x}\left[A_{1}, A_{x}\right],
$$

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$$
\dot{A}_{x}=\frac{1}{x}\left[A_{0}, A_{x}\right]-\frac{1}{1-x}\left[A_{1}, A_{x}\right],
$$

where $\dot{A}=d A / d x$. The matrix $A_{x}$ can be eliminated by setting $A_{x}=-A_{0}-$ $A_{1}-A_{\infty}$, where $A_{\infty}=-\sum_{i=1}^{3} A_{i}$ is an integral of the Schlesinger equations (1.2). The matrix $A_{\infty}$ is a constant matrix with different eigenvalues, so it is diagonalizable.

We will now follow [16], [17], [18], see also [24] and describe a connection to the Painlevé VI equation.

Let $\pm \theta_{0} / 2, \pm \theta_{1} / 2, \pm \theta_{x} / 2, \pm \theta_{\infty} / 2$ be eigenvalues of $A_{0}, A_{1}, A_{x}$ and $A_{\infty}$ and so

$$
\operatorname{tr}\left(A_{0}^{2}\right)=\frac{1}{2} \theta_{0}^{2}, \quad \operatorname{tr}\left(A_{1}^{2}\right)=\frac{1}{2} \theta_{1}^{2}, \quad \operatorname{tr}\left(A_{x}^{2}\right)=\frac{1}{2} \theta_{x}^{2}, \quad \operatorname{tr}\left(A_{\infty}^{2}\right)=\frac{1}{2} \theta_{\infty}^{2}
$$

We parametrize the traceless matrices $A_{0}, A_{1}$ as in [16], [17], [18], [24]:

$$
A_{i}=\frac{1}{2}\left(\begin{array}{cc}
z_{i} & u_{i}\left(\theta_{i}-z_{i}\right)  \tag{1.3}\\
\left(\theta_{i}+z_{i}\right) / u_{i} & -z_{i}
\end{array}\right), \quad i=0,1 .
$$

Following [16], [17], [18], [24] we replace $u_{0}$ and $u_{1}$ by two new variables $k$ and $y$ :

$$
\begin{equation*}
k=x u_{0}\left(z_{0}-\theta_{0}\right)-(1-x) u_{1}\left(z_{1}-\theta_{1}\right), \quad k y=x u_{0}\left(z_{0}-\theta_{0}\right) \tag{1.4}
\end{equation*}
$$

as a result the above isomonodromic deformation problem leads to the Painlevé VI equation :

$$
\begin{align*}
\ddot{y}= & \frac{1}{2}\left(\frac{1}{y}+\frac{1}{y-1}+\frac{1}{y-x}\right) \dot{y}^{2}-\left(\frac{1}{x}+\frac{1}{x-1}+\frac{1}{y-x}\right) \dot{y}  \tag{1.5}\\
& +\frac{y(y-1)(y-x)}{x^{2}(x-1)^{2}}\left[\alpha+\beta \frac{x}{y^{2}}+\gamma \frac{x-1}{(y-1)^{2}}+\delta \frac{x(x-1)}{(y-x)^{2}}\right]
\end{align*}
$$

characterized by the parameters $(\alpha, \beta, \gamma, \delta)$

$$
\alpha=\frac{\left(1-\theta_{\infty}\right)^{2}}{2}, \quad \beta=-\frac{\theta_{0}^{2}}{2}, \quad \gamma=\frac{\theta_{1}^{2}}{2}, \quad \delta=\frac{1-\theta_{x}^{2}}{2}
$$

We will at this point reduce the number of parameters from four to two by setting $\rho=\theta_{0}=\theta_{1}=\theta_{x}$ and $\nu=\theta_{\infty}$. These constants $\rho$ and $\nu$ parametrize $(\alpha, \beta, \gamma, \delta)$ as follows

$$
\begin{equation*}
\alpha=\frac{(1-\nu)^{2}}{2}, \quad \beta=-\frac{\rho^{2}}{2}, \quad \gamma=\frac{\rho^{2}}{2}, \quad \delta=\frac{1-\rho^{2}}{2} . \tag{1.6}
\end{equation*}
$$

In this formulation it is convenient to define

$$
\begin{align*}
& \omega_{1}^{2}=-\left(\frac{\rho^{2}}{2}+\operatorname{tr}\left(A_{1} A_{x}\right)\right)=-\frac{\rho^{2}}{4}-\frac{\nu^{2}}{4}-\frac{1}{2} \nu z_{0}  \tag{1.7}\\
& \omega_{2}^{2}=-\left(\frac{\rho^{2}}{2}+\operatorname{tr}\left(A_{0} A_{1}\right)\right)=-\frac{\rho^{2}}{4}+\frac{\nu^{2}}{4}+\frac{1}{2} \nu\left(z_{0}+z_{1}\right),  \tag{1.8}\\
& \omega_{3}^{2}=-\left(\frac{\rho^{2}}{2}+\operatorname{tr}\left(A_{0} A_{x}\right)\right)=-\frac{\rho^{2}}{4}-\frac{\nu^{2}}{4}-\frac{1}{2} \nu z_{1} . \tag{1.9}
\end{align*}
$$

The functions $\omega_{i}, i=1,2,3$ defined in (1.7)-(1.9) satisfy

$$
\begin{equation*}
\sum_{i=1}^{3} \omega_{i}^{2}=-\frac{3 \rho^{2}}{4}-\frac{\nu^{2}}{4}=-\mu^{2} \tag{1.10}
\end{equation*}
$$

which defines the scaling dimension $\mu$.
One can also prove like in [13] that $\omega_{i}, i=1,2,3$, satisfy the time dependent Euler top equations:

$$
\begin{equation*}
\frac{d \omega_{1}}{d x}=\frac{\omega_{2} \omega_{3}}{x}, \quad \frac{d \omega_{2}}{d x}=\frac{\omega_{1} \omega_{3}}{x(x-1)}, \quad \frac{d \omega_{3}}{d x}=\frac{\omega_{1} \omega_{2}}{1-x} . \tag{1.11}
\end{equation*}
$$

Next, introduce

$$
\begin{equation*}
\zeta=x(1-y) z_{0}+(1-x) y z_{1} \tag{1.12}
\end{equation*}
$$

for which we have two equations [16], [17], [18], [24]:

$$
\begin{align*}
\zeta & =-x(1-x) \dot{y}+\left(1-\theta_{\infty}\right) y(1-y)  \tag{1.13}\\
2 \theta_{\infty}\left(z_{0}+z_{1}\right) & =4 \omega_{2}^{2}+\rho^{2}-\nu^{2}=\frac{\rho^{2}(y-x)^{2}-\zeta^{2}}{x(1-x) y(1-y)}+\rho^{2}-\nu^{2} \tag{1.14}
\end{align*}
$$

From which we can determine $\omega_{2}^{2}$ in terms of $y$ and $\dot{y}$ as

$$
\omega_{2}^{2}=\frac{\rho^{2}(y-x)^{2}-\zeta^{2}}{4 x(1-x) y(1-y)}
$$

From equations (1.12), (1.13) and (1.14) we can express $z_{0}$ or $z_{1}$ in terms of $y$ and $\dot{y}$. This procedure yields:

$$
\begin{align*}
\omega_{1}^{2}= & -\frac{\rho^{2}+\nu^{2}}{4}-\frac{\rho^{2}-\nu^{2}}{4} \frac{(1-x) y}{y-x}+\frac{\nu^{2}}{2} \frac{y(y-1)}{y-x}  \tag{1.15}\\
& +\nu \frac{A}{y-x}-\frac{A_{+} A_{-}}{x(y-1)(y-x)},
\end{align*}
$$

$$
\begin{align*}
\omega_{2}^{2}= & \frac{A_{+} A_{-}}{x(1-x) y(y-1)},  \tag{1.16}\\
\omega_{3}^{2}= & -\frac{\rho^{2}+\nu^{2}}{4}-\frac{\rho^{2}-\nu^{2}}{4} \frac{x(1-y)}{y-x}-\frac{\nu^{2}}{2} \frac{y(y-1)}{y-x}  \tag{1.17}\\
& -\nu \frac{A}{y-x}-\frac{A_{+} A_{-}}{(1-x) y(y-x)},
\end{align*}
$$

where

$$
\begin{align*}
A & =\frac{1}{2}[\dot{y} x(x-1)-y(y-1)],  \tag{1.18}\\
A_{ \pm} & =\frac{1}{2} \dot{y} x(x-1)-\frac{1}{2}\left(1-\theta_{\infty}\right) y(y-1) \pm \frac{1}{2} \rho(y-x)  \tag{1.19}\\
& =A+\frac{1}{2} \nu y(y-1) \pm \frac{1}{2} \rho(y-x) .
\end{align*}
$$

There are two natural ways to further reduce the system to a one parameter system characterized by a conformal scaling dimension $\mu$ only.

1) Set $\rho^{2}=\nu^{2}$. Thus, from (1.10) $\rho^{2}=\nu^{2}=\mu^{2}$ with (cf. [13, 14, 15])

$$
\begin{equation*}
\alpha=\frac{(1 \mp \mu)^{2}}{2}, \quad \beta=-\frac{\mu^{2}}{2}, \quad \gamma=\frac{\mu^{2}}{2}, \quad \delta=\frac{1-\mu^{2}}{2}, \tag{1.20}
\end{equation*}
$$

using that $\nu= \pm \mu$. For instance, for $\nu=1 / 2$ we get $(\alpha, \beta, \gamma, \delta)=$ $(1 / 8,-1 / 8,1 / 8,3 / 8)$, while for $\nu=-1 / 2$ we get $(\alpha, \beta, \gamma, \delta)=(9 / 8,-1 / 8$, $1 / 8,3 / 8)$. In this case $\omega_{i}, i=1,2,3$ are defined through (1.7)-(1.9):

$$
\begin{equation*}
\omega_{1}^{2}=-\frac{\mu^{2}}{2}-\frac{1}{2} \nu z_{0}, \quad \omega_{2}^{2}=\frac{1}{2} \nu\left(z_{0}+z_{1}\right), \quad \omega_{3}^{2}=-\frac{\mu^{2}}{2}-\frac{1}{2} \nu z_{1}, \tag{1.21}
\end{equation*}
$$

which now yields :

$$
\begin{align*}
& \omega_{1}^{2}=-\frac{\mu^{2}}{2}\left(1+\frac{y(1-y)}{y-x}\right)+\nu \frac{A}{y-x}-\frac{1}{x(y-1)(y-x)} A_{+} A_{-},  \tag{1.22}\\
& \omega_{2}^{2}=\frac{1}{x(1-x) y(y-1)} A_{+} A_{-}, \\
& \omega_{3}^{2}=-\frac{\mu^{2}}{2}\left(1-\frac{y(1-y)}{y-x}\right)-\nu \frac{A}{y-x}-\frac{1}{(1-x) y(y-x)} A_{+} A_{-},
\end{align*}
$$

where $A$ is as in (1.18) and

$$
\begin{align*}
A_{ \pm} & =\frac{1}{2} \dot{y} x(x-1)-\frac{1}{2}(1-\nu) y(y-1) \pm \frac{1}{2} \mu(y-x)  \tag{1.25}\\
& =A+\frac{1}{2} \nu y(y-1) \pm \frac{1}{2} \mu(y-x),
\end{align*}
$$

with $\nu= \pm \mu$.
For $\nu=1 / 2$ (and $\mu^{2}=1 / 4$ ) expressions (1.15)-(1.17) agree with results of [1].

From equations (1.12) and (1.14) we find for $\rho^{2}=\nu^{2}=\mu^{2}$ :

$$
\begin{align*}
\mu^{2} \omega_{2}^{2} x(1-x) y(1-y)-\mu^{4}(y-x)^{2} / 4 & +\left[x(1-y)\left(\omega_{1}^{2}+\mu^{2} / 2\right)\right.  \tag{1.26}\\
& \left.+(1-x) y\left(\omega_{3}^{2}+\mu^{2} / 2\right)\right]^{2}=0
\end{align*}
$$

which yields a solution of the Painlevé VI equation of the form :

$$
\begin{equation*}
y(x)=x \frac{ \pm(x-1) \mu \omega_{1} \omega_{2} \omega_{3}+x \omega_{1}^{2} \omega_{2}^{2}+\omega_{1}^{2} \omega_{3}^{2}}{(x-1)^{2} \omega_{2}^{2} \omega_{3}^{2}+x^{2} \omega_{1}^{2} \omega_{2}^{2}+\omega_{1}^{2} \omega_{3}^{2}} . \tag{1.27}
\end{equation*}
$$

2) In the second case we set $\rho=0$ and therefore from (1.10) $\nu^{2}=(2 \mu)^{2}$ with $(c f .[7,8,25])$ the result that

$$
\begin{equation*}
\alpha=\frac{(1 \pm 2 \mu)^{2}}{2}, \quad \beta=0, \quad \gamma=0, \quad \delta=\frac{1}{2} \tag{1.28}
\end{equation*}
$$

and (see (1.7)-(1.9))
(1.29) $\omega_{1}^{2}=-\mu^{2}-\frac{1}{2} \nu z_{0}, \quad \omega_{2}^{2}=+\mu^{2}+\frac{1}{2} \nu\left(z_{0}+z_{1}\right), \quad \omega_{3}^{2}=-\mu^{2}-\frac{1}{2} \nu z_{1}$,
which now yields

$$
\begin{align*}
& \omega_{1}^{2}=-\frac{(y-1)(y-x)}{x}\left[\frac{A}{(y-1)(y-x)}+\frac{\nu}{2}\right]^{2}  \tag{1.30}\\
& \omega_{2}^{2}=\frac{y(y-1)}{x(1-x)}\left[\frac{A}{y(y-1)}+\frac{\nu}{2}\right]^{2}  \tag{1.31}\\
& \omega_{3}^{2}=-\frac{y(y-x)}{(1-x)}\left[\frac{A}{y(y-x)}+\frac{\nu}{2}\right]^{2} \tag{1.32}
\end{align*}
$$

From (1.14) we find for $\rho=0$

$$
\omega_{2}^{2}=-\frac{\zeta^{2}}{4 x(1-x) y(1-y)}
$$

which together with definition (1.12) of $\zeta$ and (1.30) and (1.32) yields equation

$$
\begin{equation*}
4 \mu^{2} \omega_{2}^{2} x(1-x) y(1-y)+\left[x(1-y)\left(\omega_{1}^{2}+\mu^{2}\right)+(1-x) y\left(\omega_{3}^{2}+\mu^{2}\right)\right]^{2}=0 . \tag{1.33}
\end{equation*}
$$

As a general solution of (1.33) one obtains expressions

$$
\begin{equation*}
y(x)=-x \frac{x\left(\omega_{1} \omega_{2} \mp \mu \omega_{3}\right)^{2}+\left(\omega_{1} \omega_{3} \pm \mu \omega_{2}\right)^{2}}{\left(\omega_{3}^{2}+\mu^{2}+x\left(\omega_{2}^{2}+\mu^{2}\right)\right)^{2}+4 x \mu^{2} \omega_{1}^{2}} \tag{1.34}
\end{equation*}
$$

As an example we consider the case of $\mu= \pm 1$ with

$$
\begin{equation*}
\omega_{1}=\frac{\sqrt{-b}(1-x)}{b-x}, \quad \omega_{2}=-\frac{\sqrt{-b(b-1)}}{b-x}, \quad \omega_{3}=\frac{\sqrt{b-1} x}{b-x} \tag{1.35}
\end{equation*}
$$

which satisfy the Euler top equations (1.11) and $\sum_{i=1}^{3} \omega_{i}^{2}=-1$, hence $\mu^{2}=1$. As one of two solutions to equation (1.33) we obtain

$$
\begin{equation*}
y(x)=-\frac{(b-1) x}{-b+x} \tag{1.36}
\end{equation*}
$$

which satisfies the Painlevé VI equation (1.5) with

$$
(\alpha, \beta, \gamma, \delta)=\left((1-2 \mu)^{2} / 2,0,0,1 / 2\right)=(1 / 2,0,0,1 / 2)
$$

corresponding to $\mu=1$. Note, that introducing $a=(b-1) / b, a \neq 0$ we can rewrite (1.36) as

$$
y(x)=\frac{a x}{1-(1-a) x},
$$

which appeared in [25] as a one parameter family of rational solutions to Painlevé VI equation with $\mu=1$.

As a second solution to equation (1.33) we obtain for (1.35)

$$
y(x):=-\frac{x(b-1)\left(-b+x^{2}\right)^{2}}{(-b+x)\left(x^{4}-4 b x^{3}+6 b x^{2}-4 b x+b^{2}\right)},
$$

which satisfies the Painlevé VI equation (1.5) with

$$
(\alpha, \beta, \gamma, \delta)=\left((1-2 \mu)^{2} / 2,0,0,1 / 2\right)=(9 / 2,0,0,1 / 2)
$$

corresponding to $\mu=-1$.
There is only one solution of equation (1.26):

$$
y(x)=\frac{x^{2}-b}{2(-b+x)},
$$

which yields a solution of the Painlevé VI equation (1.5) with

$$
(\alpha, \beta, \gamma, \delta)=\left((1 \pm \mu)^{2} / 2,-\mu^{2} / 2, \mu^{2} / 2,\left(1-\mu^{2}\right) / 2\right)=(2,-1 / 2,1 / 2,0)
$$

## 2. The Darboux-Egoroff equations.

The connection between the Painlevé VI equation and threedimensional Frobenius manifolds is established through the DarbouxEgoroff equations for the rotation coefficients $\beta_{i j}=\beta_{j i}$ :

$$
\begin{gather*}
\frac{\partial}{\partial u_{k}} \beta_{i j}=\beta_{i k} \beta_{k j}, \quad \text { distinct } i, j, k,  \tag{2.1}\\
\sum_{k=1}^{n} \frac{\partial}{\partial u_{k}} \beta_{i j}=0, \quad i \neq j .
\end{gather*}
$$

In addition to these equations one also assumes the conformal condition:

$$
\begin{equation*}
\sum_{k=1}^{n} u_{k} \frac{\partial}{\partial u_{k}} \beta_{i j}=-\beta_{i j} . \tag{2.3}
\end{equation*}
$$

The Darboux-Egoroff equations (2.1)-(2.2) appear as compatibility equations of a linear system :

$$
\begin{align*}
\frac{\partial \Phi_{i j}(u, z)}{\partial u_{k}} & =\beta_{i k}(u) \Phi_{k j}(u, z) \quad i \neq k  \tag{2.4}\\
\sum_{k=1}^{n} \frac{\partial \Phi_{i j}(u, z)}{\partial u_{k}} & =z \Phi_{i j}(u, z) . \tag{2.5}
\end{align*}
$$

Define the $n \times n$ matrices $\Phi=\left(\Phi_{i j}\right)_{1 \leqslant i, j \leqslant n}, B=\left(\beta_{i j}\right)_{1 \leqslant i, j \leqslant n}$ and $V_{i}=$ [ $B, E_{i i}$ ], where $\left(E_{i j}\right)_{k \ell}=\delta_{i k} \delta_{j \ell}$. Then the linear system (2.4)-(2.5) acquires the following form :

$$
\begin{align*}
\frac{\partial \Phi(u, z)}{\partial u_{i}} & =\left(z E_{i i}+V_{i}(u)\right) \Phi(u, z), \quad i=1, \ldots, n  \tag{2.6}\\
\sum_{k=1}^{n} \frac{\partial \Phi(u, z)}{\partial u_{k}} & =z \Phi(u, z) \tag{2.7}
\end{align*}
$$

The conformal case $n=3$ is very special. In that case
$V=[B, U]=\left[\left(\begin{array}{ccc}0 & \beta_{12} & \beta_{13} \\ \beta_{21} & 0 & \beta_{23} \\ \beta_{31} & \beta_{32} & 0\end{array}\right),\left(\begin{array}{ccc}u_{1} & 0 & 0 \\ 0 & u_{2} & 0 \\ 0 & 0 & u_{3}\end{array}\right)\right]=\left(\begin{array}{ccc}0 & \omega_{3} & -\omega_{2} \\ -\omega_{3} & 0 & \omega_{1} \\ \omega_{2} & -\omega_{1} & 0\end{array}\right)$
satisfies

$$
\begin{equation*}
\frac{\partial V}{\partial u_{j}}=\left[V_{j}, V\right] \tag{2.9}
\end{equation*}
$$

Note, that $\operatorname{Tr}\left(V^{2}\right)$ is an integration constant of equations (2.9), as it follows easily that $\partial \operatorname{Tr}\left(V^{2}\right) / \partial u_{j}=0$ for all $j$.

For three-dimensional Frobenius manifolds, these equations exhibit isomonodromic dependence on canonical coordinates $u$ and reduce to the class of the Painlevé VI equation (1.5) with $(\alpha, \beta, \gamma, \delta)$ parameters as in (1.20) or (1.28).

For vectorfields $I=\sum_{j=1}^{3} \partial / \partial u_{j}$ and $E=\sum_{j=1}^{3} u_{j} \partial / \partial u_{j}$ it follows from (2.9) that $I(V)=0, E(V)=0$ and accordingly $V$ is a function of one variable $x$ such that $I(x)=0, E(x)=0$. We choose

$$
\begin{equation*}
x=\frac{u_{2}-u_{1}}{u_{3}-u_{1}} . \tag{2.10}
\end{equation*}
$$

Note that $\operatorname{tr}(V)=0$ and $\operatorname{det}(V)=0$ and $V$ has eigenvalues $\mu, 0,-\mu$ where $\mu$ defines the integration constant $\operatorname{Tr}\left(V^{2}\right)$ of (2.9) through :

$$
\operatorname{Tr}\left(V^{2}\right)=-2\left(\omega_{1}^{2}+\omega_{2}^{2}+\omega_{3}^{2}\right)=2 \mu^{2}
$$

Then $\omega_{i}, i=1,2,3$ satisfy the Euler top equations (1.11) as a result of (2.9).

Note that $V(x), V\left(u_{1}, u_{2}, u_{3}\right)$, i.e. $V$ as function of $x$, respectively the $u_{i}$ 's, are connected as follows

$$
V(x)=V(0, x, 1), \quad V\left(u_{1}, u_{2}, u_{3}\right)=V\left(\frac{u_{2}-u_{1}}{u_{3}-u_{1}}\right)
$$

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Since

$$
\begin{aligned}
& \omega_{1}\left(u_{1}, u_{2}, u_{3}\right)=\left(u_{3}-u_{2}\right) \beta_{32}\left(u_{1}, u_{2}, u_{3}\right), \\
& \omega_{2}\left(u_{1}, u_{2}, u_{3}\right)=\left(u_{1}-u_{3}\right) \beta_{13}\left(u_{1}, u_{2}, u_{3}\right), \\
& \omega_{3}\left(u_{1}, u_{2}, u_{3}\right)=\left(u_{2}-u_{1}\right) \beta_{12}\left(u_{1}, u_{2}, u_{3}\right) .
\end{aligned}
$$

We find that

$$
\begin{gathered}
\omega_{1}(x)=(1-x) \beta_{23}(0, x, 1), \quad \omega_{2}(x)=-\beta_{13}(0, x, 1), \\
\omega_{3}(x)=x \beta_{12}(0, x, 1) .
\end{gathered}
$$

In other words, it suffices to know the rotation coefficients $\beta_{i j}(0, x, 1)$.

## 3. The tau-function.

We define the $\tau$-function by equation:

$$
\begin{equation*}
\frac{\partial \log \tau}{\partial u_{j}}=\frac{1}{2} \operatorname{Tr}\left(V_{j} V\right)=\sum_{i=1}^{3} \beta_{i j}^{2}\left(u_{i}-u_{j}\right)=\sum_{i, k=1}^{3} \epsilon_{i j k}^{2} \frac{\omega_{k}^{2}}{\left(u_{i}-u_{j}\right)}, \tag{3.1}
\end{equation*}
$$

in which we used $\beta_{i j}=\epsilon_{i j k} \omega_{k} /\left(u_{j}-u_{i}\right)$. This tau-function is related as

$$
\tau_{I}=\frac{1}{\sqrt{\tau}}
$$

to Dubrovin's isomonodromy tau-function $\tau_{I}[9]$.
The identity $I(\log \tau)=0$, shows that $\tau$ is a function of two variables, which again can be identified with $\chi$ and $h$ such that

$$
\begin{equation*}
h=u_{2}-u_{1} . \tag{3.2}
\end{equation*}
$$

It follows from (3.1) that

$$
E(\log \tau(u))=\frac{1}{2} \operatorname{Tr}\left(V^{2}\right)=\mu^{2} .
$$

Making use of technical identities :

$$
\frac{\partial x}{\partial u_{1}}=\frac{1}{h}(x-1) x, \quad \frac{\partial x}{\partial u_{2}}=\frac{1}{h} x, \quad \frac{\partial x}{\partial u_{3}}=-\frac{1}{h} x^{2},
$$

one easily derives

$$
\frac{\partial}{\partial u_{1}}=\frac{x(x-1)}{h} \frac{\partial}{\partial x}-\frac{\partial}{\partial h}, \quad \frac{\partial}{\partial u_{2}}=\frac{x}{h} \frac{\partial}{\partial x}+\frac{\partial}{\partial h}, \quad \frac{\partial}{\partial u_{3}}=-\frac{x^{2}}{h} \frac{\partial}{\partial x},
$$

from which

$$
E=h \frac{\partial}{\partial h}
$$

follows. Since $E(\log \tau)=h \partial \log \tau / \partial h=\mu^{2}$ we see that $\log \tau(x, h)$ decomposes as

$$
\begin{equation*}
\log \tau(x, h)=\mu^{2} \log h+\log \tau_{0}(x) \tag{3.3}
\end{equation*}
$$

where $\tau_{0}$ is a function of $x$ only.
It follows from equations (2.9) and (3.1) that

$$
\frac{\partial^{2} \log \tau}{\partial u_{i} \partial u_{j}}=-\beta_{i j}^{2}, \quad i \neq j
$$

which translates to the following parametrization of $\omega_{i}$ 's in terms of a single isomonodromic tau function :

$$
\begin{align*}
\omega_{2}^{2} & =x(x-1)\left(\frac{d^{2}}{d x^{2}} \ln \left(\tau_{0}\right)(x)\right)+(2 x-1)\left(\frac{d}{d x} \ln \left(\tau_{0}\right)(x)\right) \\
& =\frac{d}{d x}\left[x(x-1) \frac{d}{d x} \ln \left(\tau_{0}\right)(x)\right], \\
\omega_{3}^{2} & =-x^{2}(x-1)\left(\frac{d^{2}}{d x^{2}} \ln \left(\tau_{0}\right)(x)\right)-x^{2}\left(\frac{d}{d x} \ln \left(\tau_{0}\right)(x)\right)-\mu^{2} \\
& =-x^{2} \frac{d}{d x}\left[(x-1) \frac{d}{d x} \ln \left(\tau_{0}\right)(x)\right]-\mu^{2},  \tag{3.4}\\
\omega_{1}^{2} & =x(x-1)^{2}\left(\frac{d^{2}}{d x^{2}} \ln \left(\tau_{0}\right)(x)\right)+(x-1)^{2}\left(\frac{d}{d x} \ln \left(\tau_{0}\right)(x)\right) \\
& =(x-1)^{2} \frac{d}{d x}\left[x \frac{d}{d x} \ln \left(\tau_{0}\right)(x)\right] .
\end{align*}
$$

One verifies that indeed $\omega_{1}^{2}+\omega_{2}^{2}+\omega_{3}^{2}=-\mu^{2}$. Moreover,

$$
\frac{d \ln \tau_{0}}{d x}=\frac{\omega_{1}^{2}}{x(1-x)}+\frac{\omega_{2}^{2}}{x}
$$

## 4. The CKP hierarchy.

The symplectic Kadomtsev-Petviashvili or CKP hierarchy [5] can be obtained as a reduction of the KP hierarchy,

$$
\begin{align*}
& \frac{\partial}{\partial t_{n}} L=\left[\left(L^{n}\right)_{+}, L\right]  \tag{4.1}\\
& \quad \text { for } L=L(t, \partial)=\partial+\ell^{(-1)}(t) \partial^{-1}+\ell^{(-2)}(t) \partial^{-2}+\cdots,
\end{align*}
$$

where $x=t_{1}$ and $\partial=\frac{\partial}{\partial x}$, by assuming the extra condition

$$
\begin{equation*}
L^{*}=-L \tag{4.2}
\end{equation*}
$$

By taking the adjoint, i.e., ${ }^{*}$ of (4.1), one sees that $\frac{\partial L}{\partial t_{n}}=0$ for $n$ even. Date, Jimbo, Kashiwara and Miwa [5], [19] construct such L's from certain special KP wave functions $\psi(t, z)=P(t, z) e^{\sum_{i} t_{i} z^{i}}$ (recall $L(t, \partial)=P(t, \partial) \partial P(t, \partial)^{-1}$ ), where one then puts all even times $t_{n}$ equal to 0 . Recall that a KP wave function satisfies

$$
\begin{equation*}
L \psi(t, z)=z \psi(t, z), \quad \frac{\partial \psi(t, z)}{\partial t_{n}}=\left(L^{n}\right)_{+} \psi(t, z) \tag{4.3}
\end{equation*}
$$

and

$$
\begin{equation*}
\operatorname{Res}_{z} \psi(t, z) \psi^{*}(s, z)=0 \tag{4.4}
\end{equation*}
$$

The special wave functions which lead to an $L$ that has condition (4.2) satisfy

$$
\begin{equation*}
\psi^{*}(t, z)=\psi(\tilde{t},-z), \quad \text { where } \quad \tilde{t}_{i}=(-)^{i+1} t_{i} . \tag{4.5}
\end{equation*}
$$

We call such a $\psi$ a CKP wave function. Note that this implies that $L(t, \partial)^{*}=-L(\tilde{t}, \partial)$ and that

$$
\operatorname{Res}_{z} \psi(t, z) \psi(\tilde{s},-z)=0
$$

One can put all even times equal to 0 , but we will not do that here.
The CKP wave functions correspond to very special points in the Sato Grassmannian, which consists of all linear spaces

$$
W \subset H_{+} \oplus H_{-}=\mathbb{C}[z] \oplus z^{-1} \mathbb{C}\left[\left[z^{-1}\right]\right]
$$

such that the projection on $H_{+}$has finite index. Namely, $W$ corresponds to a CKP wave function if the index is 0 and for any $f(z), g(z) \in W$ one has $\operatorname{Res}_{z} f(z) g(-z)=0$. The corresponding CKP tau functions satisfy $\tau(\tilde{t})=\tau(t)$.

We will now generalize this to the multi-component case and show that a CKP reduction of the multi-component KP hierarchy gives the Darboux-Egoroff system. The $n$ component KP hierarchy [4], [20] consists of the equations in $t_{j}^{(i)}, 1 \leqslant i \leqslant n, j=1,2, \ldots$

$$
\begin{equation*}
\frac{\partial}{\partial t_{j}^{(i)}} L=\left[\left(L^{j} C_{i}\right)_{+}, L\right], \quad \frac{\partial}{\partial t_{j}^{(i)}} C_{k}=\left[\left(L^{j} C_{i}\right)_{+}, C_{k}\right] \tag{4.6}
\end{equation*}
$$

for the commuting $n \times n$-matrix pseudo-differential operators, $L, C_{i}$, $i=1,2, \ldots n$, with $\sum_{i} C_{i}=I$ of the form

$$
\begin{align*}
L & =\partial+L^{(-1)} \partial^{-1}+L^{(-2)} \partial^{-2}+\cdots,  \tag{4.7}\\
C_{i} & =E_{i i}+C_{i}^{(-1)} \partial^{-1}+C_{i}^{(-2)} \partial^{-2}+\cdots, \quad 1 \leqslant i \leqslant n
\end{align*}
$$

where $x=t_{1}^{(1)}+t_{1}^{(2)}+\cdots+t_{1}^{(n)}$. The corresponding wave function has the form

$$
\Psi(t, z)=P(t, z) \exp \left(\sum_{i=1}^{n} \sum_{j=1}^{\infty} t_{j}^{(i)} z^{j} E_{i i}\right)
$$

where $P(t, z)=I+P^{(-1)}(t) z^{-1}+\cdots$, and satisfies

$$
\begin{gather*}
L \Psi(t, z)=z \Psi(t, z), \quad C_{i} \Psi(t, z)=\Psi(t, z) E_{i i}, \\
\frac{\partial \Psi(t, z)}{\partial t_{j}^{(i)}}=\left(L^{j} C_{i}\right)_{+} \Psi(t, z) \tag{4.8}
\end{gather*}
$$

and

$$
\operatorname{Res}_{z} \Psi(t, z) \Psi^{*}(s, z)^{T}=0
$$

From this we deduce that

$$
L=P(t, \partial) \partial P(t, \partial)^{-1} \quad \text { and } \quad C_{i}=P(t, \partial) E_{i i} P(t, \partial)^{-1}
$$

Using this, the simplest equations in (4.8) are

$$
\begin{equation*}
\frac{\partial \Psi(t, z)}{\partial t_{1}^{(i)}}=\left(z E_{i i}+V_{i}(t)\right) \Psi(t, z) \tag{4.9}
\end{equation*}
$$

where $V_{i}(t)=\left[B(t), E_{i i}\right]$ and $B(t)=P^{(-1)}(t)$. In terms of the matrix coefficients $\beta_{i j}$ of $B$ we obtain (2.1) for $u_{i}=t_{1}^{(i)}$.

The Sato Grassmannian becomes vector valued, i.e.,

$$
H_{+} \oplus H_{-}=(\mathbb{C}[z])^{n} \oplus z^{-1}\left(\mathbb{C}\left[\left[z^{-1}\right]\right]\right)^{n}
$$

The same restriction as in the 1-component case (4.5), viz.,

$$
\Psi(t, z)=\Psi^{*}(\tilde{t},-z), \quad \text { where } \quad \tilde{t}_{n}^{(i)}=(-)^{n+1} t_{n}^{(i)}
$$

leads to $L^{*}(\tilde{t})=-L(t), C_{i}^{*}(\tilde{t})=C_{i}(t)$ and

$$
\begin{equation*}
\operatorname{Res}_{z} \Psi(t, z) \Psi(\tilde{s},-z)^{T}=0 \tag{4.10}
\end{equation*}
$$

which we call the multi-component CKP hierarchy. But more importantly, it also gives the restriction

$$
\begin{equation*}
\beta_{i j}(t)=\beta_{j i}(\tilde{t}) \tag{4.11}
\end{equation*}
$$

Such CKP wave functions correspond to points $W$ in the Grassmannian for which

$$
\operatorname{Res}_{z} f(z)^{T} g(-z)=\operatorname{Res}_{z} \sum_{i=1}^{n} f_{i}(z) g_{i}(-z)=0
$$

for any $f(z)=\left(f_{1}(z), f_{2}(z), \ldots, f_{n}(z)\right)^{T}, g(z)=\left(g_{1}(z), g_{2}(z), \ldots\right.$, $\left.g_{n}(z)\right)^{T} \in W$.

If we finally assume that $L=\partial$, then $\Psi, W$ also satisfy

$$
\begin{equation*}
\frac{\partial \Psi(t, z)}{\partial x}=\sum_{i=1}^{n} \frac{\partial \Psi(t, z)}{\partial t_{1}^{(i)}}=z \Psi(t, z), \quad z W \subset W \tag{4.12}
\end{equation*}
$$

and thus $\beta_{i j}$ satisfies (2.2) for $u_{i}=t_{1}^{(i)}$. Now differentiating (4.10) $n$ times to $x$ for $n=0,1,2, \ldots$ and applying (4.12) leads to

$$
\Psi(t, z) \Psi(\tilde{t},-z)^{T}=I
$$

These special points in the Grassmannian can all be constructed as follows [21]. Let $G(z)$ be an element in $G L_{n}\left(\mathbb{C}\left[z, z^{-1}\right]\right)$ that satisfies

$$
\begin{equation*}
G(z) G(-z)^{T}=I \tag{4.13}
\end{equation*}
$$

then $W=G(z) H_{+}$. Clearly, any two $f(z), g(z) \in W$ can be written as $f(z)=G(z) a(z), g(z)=G(z) b(z)$ with $a(z), b(z) \in H_{+}$, then $z f(z)=$ $z G(z) a(z)=G(z) z a(z) \in W$, since $z a(z) \in H_{+}$. Moreover,

$$
\begin{aligned}
\operatorname{Res}_{z} f(z)^{T} g(-z) & =\operatorname{Res}_{z} a(z)^{T} G(z)^{T} G(-z) b(-z) \\
& =\operatorname{Res}_{z} a(z)^{T} b(-z)=0 .
\end{aligned}
$$

We now take very special elements in this twisted loop group, i.e., elements that correspond to certain points of the Grassmannian that have a basis of homogeneous elements in $z$. Choose integers $\mu_{1} \leqslant \mu_{2} \leqslant \cdots \leqslant \mu_{n}$ such that $\mu_{n+1-j}=-\mu_{j}$. Then take $G(z)$ of the form

$$
G(z)=N(z) S^{-1}=N z^{-\mu} S^{-1}, \quad \text { where } \quad \mu=\operatorname{diag}\left(\mu_{1}, \mu_{2}, \ldots, \mu_{n}\right)
$$ and $N=\left(n_{i j}\right)_{1 \leqslant i, j \leqslant n}$ a constant matrix that satisfies

$$
\begin{equation*}
N^{T} N=\sum_{j=1}^{n}(-1)^{\mu_{j}} E_{j, n+1-j} \tag{4.14}
\end{equation*}
$$

and

$$
\begin{aligned}
S=\delta_{n, 2 m+1} E_{m+1, m+1}+\sum_{j=1}^{m} \frac{1}{\sqrt{2}}\left(E_{j j}\right. & +i E_{n+1-j, j} \\
& \left.+E_{j, n+1-j}-i E_{n+1-j, n+1-j}\right)
\end{aligned}
$$

for $n=2 m$ or $n=2 m+1$. Then [2]

$$
\sum_{i=1}^{n} \sum_{j=1}^{\infty} j t_{j}^{(i)} \frac{\partial \Psi(t, z)}{\partial t_{j}^{(i)}}=z \frac{\partial \Psi(t, z)}{\partial z}
$$

from which one deduces that

$$
\begin{equation*}
\sum_{i=1}^{n} \sum_{j=1}^{\infty} j t_{j}^{(i)} \frac{\partial \beta_{i j}}{\partial t_{j}^{(i)}}=-\beta_{i j} . \tag{4.15}
\end{equation*}
$$

We next put $t_{j}^{(i)}=0$ for all $i$ and all $j>1$ and $u_{i}=t_{1}^{(i)}$, then we obtain the situation of Section 2.

## 5. The case $\mathbf{n}=3$.

We will now give an example of the previous construction, viz., the case that $n=3$ and $-\mu_{1}=\mu_{3}=\mu \in \mathbb{N}$ and $\mu_{2}=0$. Hence, the point of the Grassmannian is given by

$$
N(z) H_{+}=N\left(\begin{array}{ccc}
z^{-\mu} & 0 & 0 \\
0 & 1 & 0 \\
0 & 0 & z^{\mu}
\end{array}\right) H_{+}
$$

More precise, let $n_{i}=\left(n_{1 i}, n_{2 i}, n_{3 i}\right)^{T}$ and $e_{1}=(1,0,0)^{T}$, $e_{2}=(0,1,0)^{T}$ and $e_{3}=(0,0,1)^{T}$, then this point of the Grassmannian has as basis

$$
\begin{array}{r}
n_{1} z^{-\mu}, n_{1} z^{1-\mu}, \ldots, n_{1} z^{-1}, n_{1}, n_{2}, n_{1} z, n_{2} z, \ldots,, n_{1} z^{\mu-1}, n_{2} z^{\mu-1} \\
e_{1} z^{\mu}, e_{2} z^{\mu}, e_{3} z^{\mu}, e_{1} z^{\mu+1}, e_{2} z^{\mu+1}, \cdots .
\end{array}
$$

Using this one can calculate in a similar way as in [22] (using the bosonfermion correspondence or vertex operator constructions) the wave function:

$$
\Psi(t, z)=P(t, z) \exp \left(\sum_{i=1}^{n} \sum_{j=1}^{\infty} t_{j}^{(i)} z^{j} E_{i i}\right)
$$

where

$$
\begin{aligned}
P_{j j}(t, z) & =\frac{\hat{\tau}\left(t_{\ell}^{(k)}-\delta_{k j}\left(\ell z^{\ell}\right)^{-1}\right)}{\hat{\tau}(t)} \\
P_{i j}(t, z) & =z^{-1} \frac{\hat{\tau}_{i j}\left(t_{\ell}^{(k)}-\delta_{k j}\left(\ell z^{\ell}\right)^{-1}\right)}{\hat{\tau}(t)} \quad \text { for } i \neq j
\end{aligned}
$$

and where

$$
\begin{aligned}
& \hat{\tau}(t)=\operatorname{det} \sum_{k=1}^{3} \sum_{i=0}^{\mu-1}\left(\sum_{j=1}^{2 \mu} n_{k 1} S_{\mu+i-j+1}\left(t^{(k)}\right) E_{3 i+k, j}\right. \\
&\left.+\sum_{j=1}^{\mu} n_{k 2} S_{i-j+1}\left(t^{(k)}\right) E_{3 i+k, 2 \mu+j}\right) .
\end{aligned}
$$

The functions $S_{i}(x)$ are the elementary Schur polynomials, defined by:

$$
\sum_{j \in \mathbb{Z}} S_{j}(x) z^{j}=e^{\sum_{k=1}^{\infty} x_{k} z^{k}}
$$

The tau function $\hat{\tau}_{i j}(t)$ is up to a multiplicative factor -1 equal to the above determinant where we replace the $j$-th row by

$$
\left(\begin{array}{llllllll}
n_{i 1} S_{\mu-1}\left(t^{(i)}\right) & \cdots & n_{i 1} S_{1}\left(t^{(i)}\right) & n_{i 1} & 0 & \cdots & 0 & 0
\end{array}\right) .
$$

Then

$$
\begin{equation*}
\beta_{i j}(t)=\frac{\hat{\tau}_{i j}(t)}{\hat{\tau}(t)} . \tag{5.1}
\end{equation*}
$$

As we have seen in Section 2 it suffices to calculate $\beta_{i j}(t)$ only for $t_{1}^{(2)}=x, t_{1}^{(3)}=1$ However we will not do that yet, we will take $t_{j}^{(1)}=s_{j}$, for $j=1,2,3, \ldots, t_{1}^{(3)}=1$ and all other $t_{i}^{(j)}=0$ and write $\beta_{i j}(s)$ for the resulting $\beta_{i j}$. In fact we will make this substitution in $\hat{\tau}(t)$ and $\hat{\tau}_{i j}(t)$. This might lead to $\hat{\tau}(s)=\hat{\tau}_{i j}(s)=0$ in such a way that $\beta_{i j}(s)=\frac{\hat{\tau}_{i j}(s)}{\hat{\tau}(s)} \neq 0$. However, as we shall see later, this will not happen.

Since, we can multiply the columns of the matrices of $\hat{\tau}_{i j}(s)$ and $\hat{\tau}(s)$ by a constant we can change the vectors $n_{1}=\left(n_{11}, n_{21}, n_{31}\right)^{T}$ and $n_{2}=\left(n_{12}, n_{22}, n_{32}\right)^{T}$. This will multiply $\hat{\tau}(s)$ by a scalar, but also $\hat{\tau}_{i j}(s)$ by the same scalar, hence $\beta_{i j}(s)$ remains the same. In a similar way $\beta_{i j}(t)$ does not change if we permute the rows of $\hat{\tau}(s)$ and $\hat{\tau}_{i j}(s)$ in the same way. We thus choose

$$
n_{1}=(\alpha, 1, a)^{T}, \quad n_{2}=(-a, 0, \alpha)^{T}, \quad \text { with } \alpha, a \neq 0 \text { and } \alpha^{2}+a^{2}=-1
$$

Then our new $\hat{\tau}(s)$ becomes:

$$
\begin{aligned}
\hat{\tau}(s)=\operatorname{det} \sum_{i=1}^{\mu}\left(\alpha E_{i, \mu+i}-\right. & a E_{i, 2 \mu+i}+\sum_{j=1}^{2 \mu} S_{\mu+i-j}(s) E_{\mu+i, j} \\
& \left.+\frac{a}{(\mu+i-j)!} E_{2 \mu+i, j}+\sum_{j=1}^{\mu} \frac{\alpha}{(i-j)!} E_{2 \mu+i, 2 \mu+j}\right),
\end{aligned}
$$

where we assume that $k!=\infty$ for $k<0$. And $\hat{\tau}_{12}(s), \hat{\tau}_{13}(s)$ and $\hat{\tau}_{32}(s)$ is -1 times the same determinant, but now with the $\mu+1$-th, $2 \mu+1$-th, $\mu+1$-th row, respectively, replaced by

$$
\left.\left.\begin{array}{l}
(0 \cdots 0 \alpha|0 \cdots 0| 0 \cdots 0), \quad(0 \cdots 0 \alpha|0 \cdots 0| 0 \cdots 0) \\
\quad\left(\left.\frac{a}{(\mu-1)!} \frac{a}{(\mu-2)!} \cdots \frac{a}{0!} \right\rvert\, 0 \cdots\right.
\end{array} \cdots \right\rvert\, 0 \cdots 0\right), \quad \text { respectively. }
$$

Next subtract a multiple of the $2 \mu+j$-th column from the $\mu+j$-th column, then one sees that

$$
\begin{align*}
\hat{\tau}(s)=\operatorname{det} \sum_{i=1}^{\mu}\left(E_{\mu+i, \mu+i}+\sum_{j=1}^{\mu} S_{\mu+i-j}(s)\right. & E_{i j}-a^{2} S_{i-j}(s) E_{i, \mu+j}  \tag{5.2}\\
& \left.+\sum_{j=1}^{2 \mu} \frac{1}{(\mu+i-j)!} E_{\mu+i, j}\right)
\end{align*}
$$

and $\hat{\tau}_{12}(s), \hat{\tau}_{13}(s), \hat{\tau}_{32}(s)$, respectively is the same determinant with the 1 -th, $\mu+1$-th, 1 -th row replaced by,

$$
\begin{gathered}
(0 \cdots 0-\alpha \mid 0 \cdots 0), \quad\left(\left.0 \cdots 0-\frac{\alpha}{a} \right\rvert\, 0 \cdots 0\right) \\
\left(\left.-\frac{a}{(\mu-1)!}-\frac{a}{(\mu-2)!}-\cdots-\frac{a}{0!} \right\rvert\, 0 \cdots 0\right), \quad \text { respectively. }
\end{gathered}
$$

Now multiply the matrix in (5.2) from the left with the matrix

$$
\sum_{1 \leqslant j \leqslant i \leqslant 2 \mu} \frac{(-1)^{i-j}}{(i-j)!} E_{i j}
$$

Then $\hat{\tau}(s)$ does not change and now becomes equal to

$$
\begin{equation*}
\hat{\tau}(s)=\operatorname{det} \sum_{i=1}^{\mu} E_{\mu+i, \mu+i}+\sum_{j=1}^{2 \mu}\left(\left(T_{2 \mu-j}^{\mu}(s)\right)^{(\mu-i)} E_{i j},\right. \tag{5.3}
\end{equation*}
$$

with

$$
\begin{equation*}
T_{k}^{\mu}(s)=\sum_{j=0}^{k-\mu} \frac{(-1)^{j}}{j!} S_{k-j}(s)-a^{2} \sum_{j=k-\mu+1}^{k} \frac{(-1)^{j}}{j!} S_{k-j}(s) \text { and } \tag{5.4}
\end{equation*}
$$

$$
\left(T_{k}^{\mu}(s)\right)^{(p)}=\frac{\partial^{p} T_{k}^{\mu}(s)}{\partial s_{1}^{p}}
$$

Multiplying the determinant of the other $\hat{\tau}_{i j}(s)$ by the same matrix, one obtains that $\hat{\tau}_{12}(s), \hat{\tau}_{13}(s), \hat{\tau}_{32}(s)$, respectively is the same determinant with the 1 -th, $\mu+1$-th, 1 -th row replaced by,

$$
\begin{aligned}
& \alpha\left(\left.\frac{(-1)^{\mu}}{(\mu-1)!} \frac{(-1)^{\mu-1}}{(\mu-2)!} \cdots \frac{-1}{0!} \right\rvert\, 0 \cdots 0\right), \\
& \frac{\alpha}{a}\left(\left.\frac{(-1)^{\mu}}{(\mu-1)!} \frac{(-1)^{\mu-1}}{(\mu-2)!} \cdots \frac{-1}{0!} \right\rvert\, 0 \cdots 0\right), \\
& -a(n 0 \cdots 01 \mid 0 \cdots 0), \quad \text { respectively. }
\end{aligned}
$$

Now permuting the first $\mu$ rows of the matrix gives that

$$
\begin{align*}
\hat{\tau}(s)= & (-)^{\frac{\mu(\mu-1)}{2}} \mathrm{~W}\left(T_{2 \mu-1}^{\mu}(s), T_{2 \mu-2}^{\mu}(s), \cdots, T_{\mu}^{\mu}(s)\right),  \tag{5.5}\\
\hat{\tau}_{12}(s)=- & (-)^{\frac{\mu(\mu-1)}{2}} \alpha \mathrm{~W}\left(T_{2 \mu-1}^{\mu}(s)+\frac{T_{2 \mu-2}^{\mu}(s)}{\mu-1}, T_{2 \mu-2}^{\mu}(s)\right. \\
& \left.+\frac{T_{2 \mu-3}^{\mu}(s)}{\mu-2}, \cdots, T_{\mu+1}^{\mu}(s)+T_{\mu}^{\mu}(s)\right),
\end{align*}
$$

$$
\begin{aligned}
\hat{\tau}_{13}(s)=- & (-)^{\frac{\mu(\mu-1)}{2}} \frac{\alpha}{a} \mathrm{~W}\left(T_{2 \mu-1}^{\mu}(s)+\frac{T_{2 \mu-2}^{\mu}(s)}{\mu-1}, T_{2 \mu-2}^{\mu}(s)\right. \\
& \left.+\frac{T_{2 \mu-3}^{\mu}(s)}{\mu-2}, \cdots, T_{\mu+1}^{\mu}(s)+T_{\mu}^{\mu}(s), T_{\mu-1}^{\mu}(s)\right) \\
\hat{\tau}_{32}(s)= & (-)^{\frac{\mu(\mu-1)}{2}} a \mathrm{~W}\left(T_{2 \mu-1}^{\mu}(s), T_{2 \mu-2}^{\mu}(s), \cdots, T_{\mu+1}^{\mu}(s)\right),
\end{aligned}
$$

where W stands for the Wronskian determinant:

$$
W\left(f_{1}(s), f_{2}(s), \ldots, f_{n}(s)\right)=\operatorname{det}\left(\frac{\partial^{i-1} f_{j}(s)}{\partial s_{1}^{i-1}}\right)_{1 \leqslant i, j \leqslant n}
$$

Thus, by (5.1) we have an expression for $\beta_{i j}(s)$ and hence can calculate the $\omega_{i}(s)$ 's. Now put all $s_{j}=0$ for $j>1$ and write $x$ for $s_{1}$, then (5.6)
$\omega_{1}(x)=-a(1-x) \frac{\mathrm{W}\left(T_{2 \mu-1}^{\mu}(x), T_{2 \mu-2}^{\mu}(x), \cdots, T_{\mu+1}^{\mu}(x)\right)}{\mathrm{W}\left(T_{2 \mu-1}^{\mu}(x), T_{2 \mu-2}^{\mu}(x), \cdots, T_{\mu}^{\mu}(x)\right)}$,
$\omega_{2}(x)=$
$-\frac{\alpha}{a} \frac{\mathrm{~W}\left(T_{2 \mu-1}^{\mu}(x)+\frac{T_{2 \mu-2}^{\mu}(x)}{\mu-1}, T_{2 \mu-2}^{\mu}(x)+\frac{T_{2 \mu-3}^{\mu}(x)}{\mu-2}, \cdots, T_{\mu+1}^{\mu}(x)+T_{\mu}^{\mu}(x), T_{\mu-1}^{\mu}(x)\right)}{\mathrm{W}\left(T_{2 \mu-1}^{\mu}(x), T_{2 \mu-2}^{\mu}(x), \cdots, T_{\mu}^{\mu}(x)\right)}$,
$\omega_{3}(x)=-\alpha x \frac{\mathrm{~W}\left(T_{2 \mu-1}^{\mu}(x)+\frac{T_{2 \mu-2}^{\mu}(x)}{\mu-1}, T_{2 \mu-2}^{\mu}(x)+\frac{T_{2 \mu-3}^{\mu}(x)}{\mu-2}, \cdots, T_{\mu+1}^{\mu}(x)+T_{\mu}^{\mu}(x)\right)}{\mathrm{W}\left(T_{2 \mu-1}^{\mu}(x), T_{2 \mu-2}^{\mu}(x), \cdots, T_{\mu}^{\mu}(x)\right)}$
satisfy the Euler top equations (1.11). We will show later that $\sum_{i=1}^{3} \omega_{i}(x)=-\mu^{2}$.

Note, see (5.5), that $\hat{\tau}(s)$ and $\hat{\tau}_{i j}(s)$ are Wronskians of functions wich satisfy

$$
\frac{\partial f(s)}{\partial s_{p}}=\frac{\partial^{p} f(s)}{\partial s_{1}^{p}}, \quad p=2,3,4, \ldots
$$

Hence they are 1-component KP tau-functions. In the next sections we will show that these Wronskians can be obtained in the (1-component) 2-vector 1-constrained CKP hierarchy.

## 6. The 2-vector 1-constrained CKP hierarchy.

The Lax operator $L$ of the (1-component) 2-vector 1-constrained CKP hierarchy can be written as (see [3])

$$
\begin{equation*}
L=\partial+\Phi_{1}(t) \partial^{-1} \Phi_{1}^{*}(t)+\Phi_{2}(t) \partial^{-1} \Phi_{2}^{*}(t) \tag{6.1}
\end{equation*}
$$

where $\Phi_{j}(t)$ is an eigenfunction and $\Phi_{j}^{*}(t)=\Phi_{j}(\tilde{t})$ an adjoint eigenfunction, satisfying

$$
\begin{equation*}
\frac{\partial \Phi_{j}(t)}{\partial t_{n}}=\left(L^{n}\right)_{+} \Phi_{j}(t), \quad \frac{\partial \Phi_{j}^{*}(t)}{\partial t_{n}}=-\left(\left(L^{*}\right)^{n}\right)_{+} \Phi_{j}^{*}(t) \tag{6.2}
\end{equation*}
$$

Recall that the Sato KP Grassmannian consists of all linear spaces

$$
W \subset H_{+} \oplus H_{-}=\mathbb{C}[z] \oplus z^{-1} \mathbb{C}\left[\left[z^{-1}\right]\right]
$$

such that the projection on $H_{+}$has finite index. We introduce a natural filtration on Grassmannian

$$
\cdots \subset H_{k+1} \subset H_{k} \subset H_{k-1} \subset H_{k-2} \subset \cdots,
$$

consisting of the linear subspaces

$$
H_{k}=\left\{\sum_{j=k}^{N} a_{j} z^{j} \mid a_{j} \in \mathbb{C}\right\} .
$$

On the space $H$ we have a bilinear form, viz. if $f(z)=\sum_{j} a_{j} z^{j}$ and $g(z)=\sum_{j} b_{j} z^{j}$ are in $H$, then we define

$$
\begin{equation*}
(f(z), g(z))=\operatorname{Res}_{z} f(z) g(z)=\sum_{j} a_{j} b_{-j-1} \tag{6.3}
\end{equation*}
$$

Then the polynomial Sato Grassmannian $\operatorname{Gr}(H)$ consists of all linear subspaces of $W \subset H$ such that

$$
\begin{equation*}
H_{k} \subset W \subset H_{\ell} \quad \text { for certain } k>\ell . \tag{6.4}
\end{equation*}
$$

The space $\operatorname{Gr}(H)$ has a subdivision into different components:

$$
\operatorname{Gr}^{(j)}(H)=\left\{W \in \operatorname{Gr}(H) \mid H_{k} \subset W, j=k-\operatorname{dim}\left(W / H_{k}\right)\right\}
$$

Clearly, the subspace $H_{k}$ belongs to $\operatorname{Gr}^{(k)}(H)$. The polynomial CKP Sato Grassmannian consists of linear subspaces of $\mathrm{Gr}^{(0)}(H)$ such that for any $f(z), g(z) \in W$ one has $(f(z), g(-z))=0$. To describe the spaces corresponding to the 2 -vector 1-constrained CKP hierarchy, such $W$ must also satisfy the following condition [11], [12], [3]. There exists a subspace

$$
\begin{equation*}
W^{\prime} \subset W \text { of codimension } 2 \text { such that } z W^{\prime} \subset W \tag{6.5}
\end{equation*}
$$

We assume that there is no larger subspace $W^{\prime}$ with $z W^{\prime} \subset W$. Let $\psi_{W}(t, z)$ be the wave function corresponding to such $W$, then the $\Phi_{j}(t)$ can be constructed as follows. Let

$$
z W+W=W \oplus \mathbb{C} z f_{1}(z) \oplus \mathbb{C} z f_{2}(z)
$$

with $f_{i}(z) \in W$. Choose two independent elements $h_{i}(z) \in \mathbb{C} f_{1}(z) \oplus \mathbb{C} f_{2}(z)$ such that

$$
\left(h_{1}(z), z h_{2}(-z)=\left(h_{2}(z), z h_{1}(-z)\right)=0,\right.
$$

then up to a scalar constant $c_{j}$ one has

$$
\Phi_{j}(t)=c_{j}\left(\psi_{W}(t, z), z h_{j}(-z)\right)
$$

## 7. Bäcklund-Darboux transformations.

In the next section we will define subspaces $W$ that are related to the tau-functions $\hat{\tau}(s)$ of Section 5. Since Bäcklund-Darboux transformations will play an important role in our construction, we will describe the elementary ones first. For $W \in \operatorname{Gr}(H)$, let $W^{\perp}$ be the orthocomplement of $W$ in $H$ w.r.t. the bilinear form (6.3). Then, $W^{\perp}$ also belongs to $\operatorname{Gr}(H)$.

For each $W \in \operatorname{Gr}(H)$ we denote the wave function corresponding to $W$ by $\psi_{W}$. The dual wave function of $\psi_{W}$, which we denote by $\psi_{W}^{*}$ can be characterized as follows [26], [10]:

Proposition 7.1. - Let $W$ and $\tilde{W}$ be two subpaces in $\operatorname{Gr}(H)$. Then $\tilde{W}$ is the space $W^{*}$ corresponding to the dual wave function, if and only if $\tilde{W}=W^{\perp}$ with $W^{\perp}$ the orthocomplement of $W$ w.r.t. the bilinear form (6.3) on $H$. Moreover

$$
\left(\psi_{W}(t, z), \psi_{W}^{*}(s, z)\right)=0 .
$$

Let $W \in \operatorname{Gr}^{(k)}(H)$ then

$$
\psi_{W}(t, z)=P_{W}(t, \partial) e^{\sum_{j=1}^{\infty} t_{j} z^{j}}, \quad \psi_{W}^{*}(t, z)=P_{W}^{*-1}(t, \partial) e^{-\sum_{j=1}^{\infty} t_{j} z^{j}}
$$

where $P_{W}(t, \partial)$ is an $k^{t h}$ order pseudo-differential operator. The corresponding KP Lax operator $L_{W}$ is equal to

$$
\begin{equation*}
L_{W}(t, \partial)=P_{W}(t, \partial) \partial P_{W}^{-1}(t, \partial) \tag{7.1}
\end{equation*}
$$

From now on we will use the notation $\psi_{W}$ and $L_{W}$ whenever we want to emphasize its dependence on a point $W$ of the Sato Grassmannian $\operatorname{Gr}(H)$.

Eigenfunctions $\Phi(t)$ and adjoint eigenfunctions $\Psi(t)$ of the KP Lax operator, satisfy (6.2) and can be expressed in wave and adjoint wave functions, viz. there exist functions $f, g \in H$ such that

$$
\begin{equation*}
\Phi(t)=\left(\psi_{W}(t, z), f(z)\right), \quad \Psi(t)=\left(\psi_{W}^{*}(t, z), g(z)\right) . \tag{7.2}
\end{equation*}
$$

Such (adjoint) eigenfunctions induce elementary Bäcklund-Darboux transformations [10]. Assume that we have the following data $W \in \operatorname{Gr}^{(k)}(H)$, $W^{\perp}, \psi_{W}(t, z)$ and $\psi_{W}^{*}(t, z)$, then the (adjoint) eigenfunctions (7.2) induce new KP wave functions:

$$
\begin{align*}
\psi_{W^{\prime}}(t, z) & =\left(\Phi(t) \partial \Phi(t)^{-1}\right) \psi_{W}(t, z)  \tag{7.3}\\
\psi_{W^{\prime}}^{*}(t, z) & =\left(\Phi(t) \partial \Phi(t)^{-1}\right)^{*-1} \psi_{W}^{*}(t, z) \\
\psi_{W^{\prime \prime}}(t, z) & =\left(-\Psi(t) \partial \Psi(t)^{-1}\right)^{*-1} \psi_{W}(t, z) \\
\psi_{W^{\prime \prime}}^{*}(t, z) & =\left(-\Psi(t) \partial \Psi(t)^{-1}\right) \psi_{W}^{*}(t, z)
\end{align*}
$$

and new tau-functions

$$
\begin{equation*}
\tau_{W^{\prime}}(t)=\Phi(t) \tau_{w}(t), \quad \tau_{W^{\prime \prime}}(t)=\Psi(t) \tau_{W}(t) \tag{7.4}
\end{equation*}
$$

where
(7.5) $W^{\prime}=\{w \in W \mid(w(z), f(z))=0\} \in \operatorname{Gr}^{(k+1)}(H), \quad W^{\prime \perp}=W^{\perp}+\mathbb{C} f$,

$$
W^{\prime \prime}=W+\mathbb{C} g \in \operatorname{Gr}^{(k-1)}(H), \quad W^{\prime \prime \perp}=\left\{w \in W^{\perp} \mid(w(z), g(z))=0\right\}
$$

Now applying $n$ consecutive elementary Bäcklund-Darboux transformations such that one obtains

$$
W^{\prime}=\left\{w \in W \mid\left(w(z), f_{i}(z)\right)=0, i=1,2, \ldots, n\right\}
$$

from $W$, then (see [10])

$$
\tau_{W^{\prime}}(t)=W\left(\Phi_{1}(t), \Phi_{2}(t), \ldots, \Phi_{n}(t)\right) \tau_{W}(t)
$$

where one has to take derivatives w.r.t. $x$ and where

$$
\Phi_{j}(t)=\left(\psi_{W}(t, z), f_{j}(z)\right)
$$

and

$$
\begin{equation*}
\psi_{W^{\prime}}(t, z)=\frac{1}{\tau_{W^{\prime}}(t)} W\left(\Phi_{1}(t), \Phi_{2}(t), \ldots, \Phi_{n}(t), \psi_{W}(t, z)\right) \tag{7.6}
\end{equation*}
$$

## 8. Subspaces $W_{\mu}$.

In this section we will construct Subspaces $W_{\mu}$ in the 2-vector 1constrained CKP hierarchy related to the solutions of Section 5 of the time-dependent Euler top equations. Let $a \in \mathbb{C}$ with $a \neq 0, \pm i$ be the parameter of Section 5 . Define $b=-a^{2}$, then $b \neq 0,1$ and introduce

$$
\begin{equation*}
r_{0}(z)=b e^{z} . \tag{8.1}
\end{equation*}
$$

Unfortunately $r_{0}(z)$ is not an element of $H$. However, since we always assume that $H_{k} \subset W$ for $k \gg 0$, we will write $e^{z}$ and will mean in fact $\sum_{j=0}^{N} \frac{z^{j}}{j!}$ with $N>2 k \gg 0$. Having this in mind, we define for $i=1,2, \cdots$ the elements.

$$
\begin{equation*}
r_{i}(z)=z^{-i}\left(b e^{z}+(1-b) \sum_{j=0}^{i-1} \frac{z^{j}}{j!}\right) \tag{8.2}
\end{equation*}
$$

Note that

$$
\begin{equation*}
r_{i+1}(z)=z^{-1}\left(r_{i}(z)+\frac{1-b}{i!}\right) \tag{8.3}
\end{equation*}
$$

and a straightforward calculation shows:
Lemma 8.1. - For $i, j>0$

$$
\left(r_{i}(z), r_{j}(-z)\right)=0
$$

Now define for $\mu=1,2, \cdots$, the point $W_{\mu} \in \operatorname{Gr}(H)$

$$
\begin{equation*}
W_{\mu}=\text { linear } \operatorname{span}\left\{r_{1}(z), r_{2}(z), \ldots, r_{\mu}(z)\right\} \oplus H_{\mu} \tag{8.4}
\end{equation*}
$$

From now on we will assume that $\mu$ can also be 0 , then $W_{0}=H_{0}$. From the definition (8.2) of the functions $r_{i}(z)$ it is clear that

$$
\left(f(z), r_{i}(-z)\right)=(f(z), g(-z))=0 \quad \text { for all } f(z), g(z) \in H_{\mu}, \quad 0 \leqslant i \leqslant \mu
$$

From Lemma 8.1 it is then clear that $W_{\mu}$ satisfies the CKP condition, to be more precise

Proposition 8.1. - $\quad W_{\mu} \in \operatorname{Gr}^{(0)}(H)$ satisfies the CKP condition and

$$
W_{\mu}=\left\{f(z) \in H_{-\mu} \mid\left(f(z), r_{i}(-z)\right)=0, \text { for } 1 \leqslant i \leqslant \mu\right\} .
$$

Next define the subspace $U_{\mu} \subset W_{\mu}$ of codimension 2 for $\mu \geqslant 2$, of codimension 1 if $\mu=1$ and of codimension 0 if $\mu=0$ by

$$
\begin{equation*}
U_{\mu}=\left\{f(z) \in W_{\mu} \mid(f(z), 1)=\left(f(z), r_{0}(-z)\right)=0\right\} \tag{8.5}
\end{equation*}
$$

Now let $g(z) \in U_{\mu}$, then $z g(z) \in H_{-\mu+1}$ and $\left(z g(z), r_{j}(-z)\right)=0$ for all $1 \leqslant j \leqslant \mu$.

This follows from the following observation:

$$
\left(z g(z), r_{j}(-z)\right)=\left(g(z), z r_{j}(-z)\right)=\left(g(z),-r_{j-1}(-z)-\frac{1-b}{(j-1)!}\right)=0
$$

for $j=1,2, \ldots, \mu$, since $g(z)$ is perpendicular to $1, r_{i}(-z)$ for $0 \leqslant i \leqslant \mu$. Hence, $W_{\mu}$ has a subspace $W^{\prime}$ of codimension 2 such that $z W^{\prime} \subset W_{\mu}$, hence

Proposition 8.2. - $W_{\mu}$ with $\mu>1$ also belongs to the 2 -vector 1-constrained KP hierarchy.

Note that $W_{1}$ belongs to the 1-vector 1-constrained KP. From Proposition 8.1 and Section 7 it is clear that $W_{\mu}$ can be obtained from $H_{-\mu} \in$ $\mathrm{Gr}^{(\mu)}(H)$ by $\mu$ consecutive elementary Bäcklund-Darboux transformations. Now $\tau_{H_{-\mu}}=1$ and $\psi_{H_{-\mu}}(t, z)=z^{-\mu} \psi_{0}(t, z)$ where $\psi_{0}(t, z)=e^{\sum_{i=0}^{\infty} t_{i} z^{i}}$. Let $\tau_{\mu}(t)=\tau_{W_{\mu}}(t)$ and $\psi_{\mu}(t, z)=\psi_{W_{\mu}}(t, z)$, then

$$
\begin{equation*}
\tau_{\mu}(t)=W\left(R_{1}^{\mu}(t), R_{2}^{\mu}(t), \ldots, R_{\mu}^{\mu}(t)\right) \tag{8.6}
\end{equation*}
$$

where

$$
\begin{align*}
R_{i}^{\mu}(t) & :=\left(z^{-\mu} \psi_{0}(t, z), r_{i}(-z)\right)=\left(\psi_{0}(t, z), z^{-\mu} r_{i}(-z)\right)  \tag{8.7}\\
& =\sum_{k=0}^{i-1} \frac{(-1)^{k-i}}{k!} S_{\mu+i-k-1}(t)+b \sum_{k=i}^{\mu+i-1} \frac{(-1)^{k-i}}{k!} S_{\mu+i-k-1}(t) .
\end{align*}
$$

Here $S_{k}(t)$ are the elementary Schur functions. The corresponding wave function is given by

$$
\begin{equation*}
\psi_{\mu}(t, z)=\frac{1}{\tau_{\mu}(t)} W\left(\left(R_{1}^{\mu}(t), R_{2}^{\mu}(t), \ldots, R_{\mu}^{\mu}(t), z^{-\mu} \psi_{0}(t, z)\right)\right. \tag{8.8}
\end{equation*}
$$

Note that

$$
R_{i}^{\mu}(t)=(-)^{i} T_{\mu+i-1}^{\mu}(t), \quad \text { with } b=-a^{2}
$$

Hence

$$
\tau_{\mu}(s)=(-)^{\frac{\mu(\mu+1)}{2}} \hat{\tau}(s) .
$$

In order to describe the other tau-functions of Section 5, we want to find the right expression for the Lax operator $L=L_{\mu}=L_{W_{\mu}}$. For this we study $W_{\mu}$ and $z W_{\mu}$. Recall from (8.4) that

$$
W_{\mu}=\text { linear } \operatorname{span}\left\{r_{1}(z), r_{2}(z), \ldots, r_{\mu}(z)\right\} \oplus H_{\mu}
$$

and

$$
W_{\mu}^{\perp}=\text { linear } \operatorname{span}\left\{r_{1}(-z), r_{2}(-z), \ldots, r_{\mu}(-z)\right\} \oplus H_{\mu},
$$

hence

$$
z W_{\mu}=\text { linear } \operatorname{span}\left\{z r_{1}(z), z r_{2}(z), \ldots, z r_{\mu}(z)\right\} \oplus H_{\mu+1}
$$

$$
\left(z W_{\mu}\right)^{\perp}=\text { linear } \operatorname{span}\left\{z^{-1} r_{1}(-z), z^{-1} r_{2}(-z), \ldots, z^{-1} r_{\mu}(-z)\right\} \oplus H_{\mu-1}
$$

From now on we assume in this section that $\mu>1$. In that case it is straightforward to check that

$$
z W_{\mu}+W_{\mu}=W_{\mu} \oplus \mathbb{C} z r_{1}(z) \oplus \mathbb{C} z r_{2}(z)
$$

Putting

$$
\begin{equation*}
h_{1}(z)=r_{1}(z)-r_{2}(z) \quad \text { and } \quad h_{2}(z)=r_{2}(z), \tag{8.9}
\end{equation*}
$$

one easily verifies that

$$
\begin{align*}
\left(h_{1}(z), z h_{2}(-z)\right) & =\left(h_{2}(z), z h_{1}(-z)\right)=\left(h_{1}(-z), z h_{2}(z)\right)  \tag{8.10}\\
& =\left(h_{2}(-z), z h_{1}(z)\right)=0 .
\end{align*}
$$

Using the construction of the Lax operator as in Section 6 we see that

$$
\begin{align*}
L_{\mu} & =\partial+\sum_{i=1}^{2} c_{i}\left(\psi_{\mu}(t, z), z h_{i}(-z)\right) \partial^{-1}\left(\psi_{\mu}^{*}(t, z), z h_{i}(z)\right)  \tag{8.11}\\
& =\partial+\sum_{i=1}^{2} c_{i}\left(\psi_{\mu}(t, z), z h_{i}(-z)\right) \partial^{-1}\left(\psi_{\mu}(\tilde{t}, z), z h_{i}(-z)\right)
\end{align*}
$$

We want to determine the $c_{i}$ 's, for this we let $L_{\mu}$ act on $\psi_{\mu}$, this gives

$$
z \psi_{\mu}(t, z)=\frac{\partial \psi_{\mu}(t, z)}{\partial x}+\sum_{i=1}^{2} c_{i}\left(\psi_{\mu}(t, z), z h_{i}(-z)\right) \partial^{-1}
$$

$$
\begin{equation*}
\cdot\left(\psi_{\mu}^{*}(t, z), z h_{i}(z)\right) \psi_{\mu}(t, z) \tag{8.12}
\end{equation*}
$$

$$
\begin{aligned}
&=\frac{\partial \psi_{\mu}(t, z)}{\partial x}+\sum_{i=1}^{2} c_{i}\left(\psi_{\mu}(t, z), z h_{i}(-z)\right)\left(\psi_{\mu}(\tilde{t}, z),\right. \\
&\left.z h_{i}(-z)\right) \\
& \cdot \psi_{W_{\mu}+\mathbb{C} z h_{i}(z)}(t, z)
\end{aligned}
$$

Now take the bilinear form with the elements $h_{j}(-z)$. Since (8.10) holds, and $h_{1}(-z)$ (resp. $h_{2}(-z)$ ) is perpendicular to $W_{\mu}$ and $W_{\mu}+\mathbb{C} z h_{2}(z)$ (resp. $\left.W_{\mu}+\mathbb{C} z h_{1}(z)\right)$ we obtain

$$
\begin{aligned}
\left(\psi_{\mu}(t, z), z h_{i}(-z)\right)=c_{i}\left(\psi_{\mu}(t, z), z h_{i}(-z)\right) & \left(\psi_{\mu}(\tilde{t}, z), z h_{i}(-z)\right) \\
\cdot & \left(\psi_{W_{\mu}+\mathbb{C} z h_{i}(z)}(t, z), h_{i}(-z)\right) .
\end{aligned}
$$

Hence

$$
\begin{equation*}
c_{i}=\left(\left(\psi_{\mu}(\tilde{t}, z), z h_{i}(-z)\right)\left(\psi_{W_{\mu}+\mathbb{C} z h_{i}(z)}(t, z), h_{i}(-z)\right)\right)^{-1} \tag{8.13}
\end{equation*}
$$

We are now going to determine these $c_{i}$ 's. Note that

$$
\begin{equation*}
z h_{1}(z)=r_{0}(z)-r_{1}(z) \quad \text { and } \quad z h_{2}(z)=1-b+r_{1}(z) \tag{8.14}
\end{equation*}
$$

Using this we see that

$$
\begin{aligned}
& W_{\mu}+\mathbb{C} z h_{1}(z)=\text { linear } \operatorname{span}\left\{r_{0}(z), r_{1}(z), \ldots r_{\mu}(z)\right\}+H_{\mu} \\
& W_{\mu}+\mathbb{C} z h_{2}(z)=\text { linear } \operatorname{span}\left\{1, r_{1}(z), r_{2}(z), \ldots r_{\mu}(z)\right\}+H_{\mu} .
\end{aligned}
$$

The fact that

$$
\left(r_{0}(z), r_{1}(-z)\right)=-b,\left(r_{0}(z), r_{i}(-z)\right)=0
$$

and

$$
\left(1, r_{j}(-z)\right)=-\frac{1}{(j-1)!} \text { for } i>1, j \geqslant 1
$$

gives the following, more convenient description of $W_{\mu}+\mathbb{C} z h_{1}(z)$ and $W_{\mu}+\mathbb{C} z h_{2}(z):$

$$
\begin{aligned}
W_{\mu}+\mathbb{C} z h_{1}(z)=\left\{f(z) \in H_{-\mu} \mid\left(f(z), r_{i}(-z)\right)=0\right. \\
\text { for } i=2,3, \ldots, \mu\} \\
W_{\mu}+\mathbb{C} z h_{2}(z)=\left\{f(z) \in H_{-\mu} \left\lvert\,\left(f(z), r_{i+1}(-z)-\frac{r_{i}(-z)}{i}\right)=0\right.\right. \\
\text { for } i=1,2, \ldots, \mu-1\} .
\end{aligned}
$$

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Thus,

$$
\begin{align*}
& \tau_{W_{\mu}+\mathbb{C} z h_{1}(z)}(t)= \operatorname{det}\left(\left(\psi_{0}(t, z), z^{i-\mu-1} r_{j+1}(-z)\right)\right)_{1 \leqslant i, j \leqslant \mu-1} \\
&= W\left(R_{2}^{\mu}(t), R_{3}^{\mu}(t), \ldots, R_{\mu}^{\mu}(t)\right), \\
& \tau_{W_{\mu}+\mathbb{C} z h_{2}(z)}(t)= \operatorname{det}\left(\psi_{0}(t, z), z^{i-\mu-1}\left(r_{j+1}(-z)\right.\right.  \tag{8.16}\\
&\left.\left.-\frac{r_{j}(-z)}{j}\right)\right)_{1 \leqslant i, j \leqslant \mu-1} \\
&= W\left(R_{2}^{\mu}(t)-R_{1}^{\mu}(t), R_{3}^{\mu}(t)-\frac{R_{2}^{\mu}(t)}{2}\right. \\
&\left.\ldots, R_{\mu}^{\mu}(t)-\frac{R_{\mu-1}^{\mu}(t)}{\mu-1}\right) .
\end{align*}
$$

and the corresponding wave functions are equal to:
(8.17) $\quad \psi_{W_{\mu}+\mathbb{C} z h_{1}(z)}(t, z)=\frac{1}{\tau_{W_{\mu}+\mathbb{C} z h_{1}(z)}(t)} W\left(W\left(R_{2}^{\mu}(t), R_{3}^{\mu}(t)\right.\right.$,

$$
\left.\ldots, R_{\mu}^{\mu}(t), z^{-\mu} \psi_{0}(t, z)\right)
$$

and
(8.18) $\psi_{W_{\mu}+\mathbb{C} z h_{2}(z)}(t, z)=\frac{1}{\tau_{W_{\mu}+\mathbb{C} z h_{2}(z)}(t)} W\left(R_{2}^{\mu}(t)-R_{1}^{\mu}(t), R_{3}^{\mu}(t)-\frac{R_{2}^{\mu}(t)}{2}\right.$,

$$
\left.\ldots, R_{\mu}^{\mu}(t)-\frac{R_{\mu-1}^{\mu}(t)}{\mu-1}, z^{-\mu} \psi_{0}(t, z)\right)
$$

From this we deduce that

$$
\begin{align*}
\left(\psi_{W_{\mu}+\mathbb{C} z h_{1}(z)}(t, z), h_{1}(-z)\right) & =\left(\psi_{W_{\mu}+\mathbb{C} z h_{1}(z)}(t, z), r_{1}(-z)\right) \\
& =(-)^{\mu-1} \frac{\tau_{\mu}(t)}{\tau_{W_{\mu}+\mathbb{C} z h_{1}(z)}(t)},  \tag{8.19}\\
\left(\psi_{W_{\mu}+\mathbb{C} z h_{2}(z)}(t, z), h_{2}(-z)\right) & =\left(\psi_{W_{\mu}+\mathbb{C} z h_{2}(z)}(t, z), r_{2}(-z)\right) \\
& =(-)^{\mu-1} \frac{\tau_{\mu}(t)}{\tau_{W_{\mu}+\mathbb{C} z h_{2}(z)}(t)} .
\end{align*}
$$

For the other eigenfunctions we find, using (8.14):

$$
\begin{align*}
& \left(\psi_{\mu}(\tilde{t}, z), z h_{1}(-z)\right)=(-)^{\mu+1} \frac{\tau_{W^{\prime}}(\tilde{t})}{\tau_{\mu}(\tilde{t})}  \tag{8.20}\\
& \left(\psi_{\mu}(\tilde{t}, z), z h_{2}(-z)\right)=(b-1) \frac{\tau_{W^{\prime \prime}}(\tilde{t})}{\tau_{\mu}(\tilde{t})}
\end{align*}
$$

where

$$
\begin{align*}
W^{\prime} & =\left\{f(z) \in H_{-\mu} \mid\left(f(z), r_{i}(-z)\right)=0 \text { for } i=0,1, \ldots, \mu\right\},  \tag{8.21}\\
W^{\prime \prime} & =\left\{f(z) \in H_{-\mu} \mid(f(z), 1)=0\right. \text { and } \\
& \left.\quad\left(f(z), r_{i}(-z)\right)=0 \text { for } i=1,2, \ldots, \mu\right\}
\end{align*}
$$

and

$$
\begin{align*}
\tau_{W^{\prime}}(t) & =W\left(R_{0}^{\mu}(t), R_{1}^{\mu}(t), R_{2}^{\mu}(t), \ldots, R_{\mu}^{\mu}(t)\right)  \tag{8.22}\\
\tau_{W^{\prime \prime}}(t) & =W\left(R_{1}^{\mu}(t), R_{2}^{\mu}(t), \ldots, R_{\mu}^{\mu}(t), S_{\mu-1}(t)\right)
\end{align*}
$$

Now combining (8.13), (8.20) and (8.19), we find that

$$
\begin{align*}
c_{1} & =\frac{\tau_{\mu}(\tilde{t}) \tau_{W_{\mu}+\mathbb{C} z h_{1}(z)}(t)}{\tau_{W^{\prime}}(\tilde{t}) \tau_{\mu}(t)}=\frac{\tau_{W_{\mu}+\mathbb{C} z h_{1}(z)}(t)}{\tau_{W^{\prime}}(\tilde{t})},  \tag{8.23}\\
c_{2} & =(-)^{\mu-1}(b-1)^{-1} \frac{\tau_{\mu}(\tilde{t}) \tau_{W_{\mu}+\mathbb{C} z h_{2}(z)}(t)}{\tau_{W^{\prime \prime}}(\tilde{t}) \tau_{\mu}(t)} \\
& =(-)^{\mu-1}(b-1)^{-1} \frac{\tau_{W_{\mu}+\mathbb{C} z h_{2}(z)}(t)}{\tau_{W^{\prime \prime}(\tilde{t})}},
\end{align*}
$$

since $\tau_{\mu}(\tilde{t})=\tau_{\mu}(t)$. Since these $c_{i}$ 's are just constants, it suffices to substitute $t=0$, i.e. $t_{j}=0$ for all $j=1,2,3, \ldots$, in (8.23), this gives

$$
\begin{equation*}
c_{1}=\frac{\tau_{W_{\mu}+\mathbb{C} z h_{1}(z)}(0)}{\tau_{W^{\prime}}(0)}, \quad c_{2}=(-)^{\mu-1}(b-1)^{-1} \frac{\tau_{W_{\mu}+\mathbb{C} z h_{2}(z)}(0)}{\tau_{W^{\prime \prime}}(0)} . \tag{8.24}
\end{equation*}
$$

We now calculate these tau-functions for $t=0$ :

$$
\begin{align*}
\tau_{W_{\mu}+\mathbb{C} z h_{1}(z)}(0) & =\operatorname{det}\left(\left(z^{i-\mu-1}, r_{j+1}(-z)\right)\right)_{1 \leqslant i, j \leqslant \mu-1}  \tag{8.25}\\
& =\operatorname{det}\left(\frac{(-)^{\mu-i} b}{(\mu+j-i+1)!}\right)_{1 \leqslant i, j \leqslant \mu-1} \\
& =(-)^{\frac{\mu(\mu-1)}{2}} b^{\mu-1} \operatorname{det}\left(\frac{1}{(\mu+j-i+1)!}\right)_{1 \leqslant i, j \leqslant \mu-1} \\
& =(-)^{\frac{\mu(\mu-1)}{2}} b^{\mu-1} S_{\mu+1, \mu+1, \ldots, \mu+1}^{(\mu-1)}(1,0,0, \ldots),
\end{align*}
$$

where (see [23])

$$
S_{\lambda_{1}, \lambda_{2}, \ldots, \lambda_{k}}^{(k)}\left(t_{1}, t_{2}, t_{3}, \ldots\right)=\operatorname{det}\left(S_{\lambda_{i}+j-i}\left(t_{1}, t_{2}, t_{3}, \ldots\right)\right)_{1 \leqslant i, j \leqslant k},
$$

the Schur function corresponding to the partition $\lambda_{1}, \lambda_{2}, \ldots, \lambda_{k}$. Here $S_{\ell}\left(t_{1}, t_{2}, t_{3}, \ldots\right)$ is the elementary Schur function. In a similar way one shows that

$$
\begin{align*}
\tau_{W^{\prime}}(0) & =\operatorname{det}\left(\left(z^{i-\mu-1}, r_{j-1}(-z)\right)\right)_{1 \leqslant i, j \leqslant \mu+1}  \tag{8.26}\\
& =(-)^{\frac{\mu(\mu-1)}{2}+1} b^{\mu} S_{\mu-1, \mu-1, \ldots, \mu-1}^{(\mu+1)}(1,0,0, \ldots)
\end{align*}
$$

and

$$
\begin{align*}
\tau_{W^{\prime \prime}}(0) & =\operatorname{det}\left(\begin{array}{cccc}
\left(z^{-\mu}, r_{1}(-z)\right) & \cdots & \left(z^{-\mu}, r_{\mu}(-z)\right) & \left(z^{-\mu}, 1\right) \\
\left(z^{1-\mu}, r_{1}(-z)\right) & \cdots & \left(z^{1-\mu}, r_{\mu}(-z)\right) & \left(z^{1-\mu}, 1\right) \\
\vdots & & \vdots & \vdots \\
\left(r_{1}(-z), 1\right) & \cdots & \left(r_{\mu}(-z), 1\right) & (1,1)
\end{array}\right)  \tag{8.27}\\
& =(-)^{\frac{\mu(\mu-1)}{2}} b^{\mu-1} S_{\mu, \mu, \ldots, \mu, \mu-1}^{(\mu)}(1,0,0, \ldots) .
\end{align*}
$$

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And finally the most complicated one:

$$
\begin{align*}
\tau_{W_{\mu}+\mathbb{C} z h_{2}(z)}(0) & =\operatorname{det}\left(\left(z^{i-\mu-1},\left(r_{j+1}(-z)-\frac{r_{j}(-z)}{j}\right)\right)\right)_{1 \leqslant i, j \leqslant \mu-1} \\
& =\operatorname{det}\left(\frac{(-)^{\mu-i} b}{(\mu+j-i+1)!}-\frac{(-)^{\mu-i} b}{(\mu+j-i)!j}\right)_{1 \leqslant i, j \leqslant \mu-1}  \tag{8.28}\\
& =(-)^{\frac{(\mu-1)(\mu+2)}{2}} b^{\mu-1} \operatorname{det}\left(\frac{\mu-i+1}{(\mu+j-i+1)!j}\right)_{1 \leqslant i, j \leqslant \mu-1} \\
& =(-)^{\frac{(\mu-1)(\mu+2)}{2}} \mu b^{\mu-1} \operatorname{det}\left(\frac{1}{(\mu+j-i+1)!}\right)_{1 \leqslant i, j \leqslant \mu-1} \\
& =(-)^{\frac{(\mu-1)(\mu+2)}{2}} \mu b^{\mu-1} S_{\mu+1, \mu+1, \ldots, \mu+1}^{(\mu-1)}(1,0,0, \ldots) .
\end{align*}
$$

We conclude from all this that

$$
\begin{align*}
& c_{1}=-b^{-1} \frac{S_{\mu+1, \mu+1, \ldots, \mu+1}^{(\mu-1)}(1,0,0, \ldots)}{S_{\mu-1, \mu-1, \ldots, \mu-1}^{(\mu+1)}(1,0,0, \ldots)}  \tag{8.29}\\
& c_{2}=(b-1)^{-1} \mu \frac{S_{\mu+1, \mu+1, \ldots, \mu+1}^{(\mu-1)}(1,0,0, \ldots)}{S_{\mu, \mu, \ldots, \mu, \mu-1}^{(\mu)}(1,0,0, \ldots)}
\end{align*}
$$

Now using the fact that

$$
\begin{aligned}
S_{\mu+1, \mu+1, \ldots, \mu+1}^{(\mu-1)}(1,0,0, \ldots) & =S_{\mu-1, \mu-1, \ldots, \mu-1}^{(\mu+1)}(1,0,0, \ldots)=\mu \frac{\prod_{i=1}^{\mu-1}(i!)^{2}}{\prod_{i=1}^{2 \mu-1} i!} \\
\quad S_{\mu, \mu, \ldots, \mu, \mu-1}^{(\mu)}(1,0,0, \ldots) & =\mu^{2} \frac{\prod_{i=1}^{\mu-1}(i!)^{2}}{\prod_{i=1}^{2 \mu-1} i!}
\end{aligned}
$$

we obtain

$$
\begin{equation*}
c_{1}=-\frac{1}{b} \quad \text { and } \quad c_{2}=\frac{1}{b-1} . \tag{8.30}
\end{equation*}
$$

So finally

$$
\begin{align*}
L_{\mu}= & \partial-b^{-1}\left(\psi_{\mu}(t, z), z h_{1}(-z)\right) \partial^{-1}\left(\psi_{\mu}(\tilde{t}, z), z h_{1}(-z)\right) \\
& +(b-1)^{-1}\left(\psi_{\mu}(t, z), z h_{2}(-z)\right) \partial^{-1}\left(\psi_{\mu}(\tilde{t}, z), z h_{2}(-z)\right)  \tag{8.31}\\
= & \partial+\left(\psi_{\mu}(t, z),(-)^{\mu+1} \sqrt{-b} e^{-z}\right) \partial^{-1}\left(\psi_{\mu}(\tilde{t}, z),(-)^{\mu+1} \sqrt{-b} e^{-z}\right) \\
& +\left(\psi_{\mu}(t, z), \sqrt{b-1}\right) \partial^{-1}\left(\psi_{\mu}(\tilde{t}, z), \sqrt{b-1}\right) .
\end{align*}
$$

We have added the term $(-)^{\mu+1}$ here, in order to get rid of this term later
on in this section. Note that (see (8.20))

$$
\begin{aligned}
\left(\psi_{\mu}(t, z),(-)^{\mu+1} \sqrt{-b} e^{-z}\right) & =\frac{1}{\sqrt{-b}} \frac{\tau_{W^{\prime}}(t)}{\tau_{\mu}(t)} \\
& =\frac{1}{\sqrt{-b}} \frac{W\left(R_{0}^{\mu}(t), R_{1}^{\mu}(t), R_{2}^{\mu}(t), \ldots, R_{\mu}^{\mu}(t)\right)}{W\left(R_{1}^{\mu}(t), R_{2}^{\mu}(t), \ldots, R_{\mu}^{\mu}(t)\right)} \\
\left(\psi_{\mu}(t, z), \sqrt{b-1}\right)= & \sqrt{b-1} \frac{\tau_{W^{\prime \prime}}(t)}{\tau_{\mu}(t)} \\
& =\sqrt{b-1} \frac{W\left(R_{1}^{\mu}(t), R_{2}^{\mu}(t), \ldots, R_{\mu}^{\mu}(t), S_{\mu-1}(t)\right)}{W\left(R_{1}^{\mu}(t), R_{2}^{\mu}(t), \ldots, R_{\mu}^{\mu}(t)\right)}
\end{aligned}
$$

Using (8.23), (8.16) and (8.30) we find that also

$$
\begin{aligned}
& \begin{aligned}
&\left(\psi_{\mu}(\tilde{t}, z),(-)^{\mu+1} \sqrt{-b} e^{-z}\right)=\sqrt{-b} \frac{\tau_{W_{\mu}+\mathbb{C} z h_{1}(z)}(t)}{\tau_{\mu}(t)} \\
&=\sqrt{-b} \frac{W\left(R_{2}^{\mu}(t), R_{3}^{\mu}(t), \ldots, R_{\mu}^{\mu}(t)\right)}{W\left(R_{1}^{\mu}(t), R_{2}^{\mu}(t), \ldots, R_{\mu}^{\mu}(t)\right)}, \\
&\left(\psi_{\mu}(\tilde{t}, z), \sqrt{b-1}\right) \\
&=(-)^{\mu-1} \sqrt{b-1} \frac{\tau_{W_{\mu}+\mathbb{C} z h_{2}(z)}(t)}{\tau_{\mu}(t)} \\
&=(-)^{\mu-1} \sqrt{b-1} \frac{W\left(R_{2}^{\mu}(t)-R_{1}^{\mu}(t), R_{3}^{\mu}(t)-\frac{R_{2}^{\mu}(t)}{2}, \ldots, R_{\mu}^{\mu}(t)-\frac{R_{\mu-1}^{\mu}(t)}{\mu-1}\right)}{W\left(R_{1}^{\mu}(t), R_{2}^{\mu}(t), \ldots, R_{\mu}^{\mu}(t)\right)} .
\end{aligned} .
\end{aligned}
$$

We thus obtain in this way that

$$
\beta_{12}(s)=\left(\psi_{\mu}(\tilde{s}, z), \sqrt{b-1}\right) \quad \text { with } \alpha=\sqrt{b-1}
$$

and

$$
\beta_{32}(s)=\left(\psi_{\mu}(\tilde{s}, z),(-)^{\mu+1} \sqrt{-b} e^{-z}\right) \quad \text { with } a=(-)^{\mu+1} \sqrt{-b} .
$$

To obtain $\beta_{13}(s)$, we calculate the so-called squared eigenfunction potential

$$
\partial^{-1}\left(\psi_{\mu}(\tilde{t}, z), \sqrt{b-1}\right)\left(\psi_{\mu}(t, z),(-)^{\mu+1} \sqrt{-b} e^{-z}\right)
$$

of $\left(\psi_{\mu}(\tilde{t}, z), \sqrt{b-1}\right)$ and $\left(\psi_{\mu}(t, z),(-)^{\mu+1} \sqrt{-b} e^{-z}\right)$. Let

$$
w(z)=b_{1} r_{1}(-z)+\sum_{i=1}^{\mu-1} b_{i+1}\left(r_{i+1}(-z)-\frac{r_{i}(-z)}{i}\right)+\sum_{j>\mu} b_{j} z^{j},
$$

be an arbitrary element of $W_{\mu}^{\perp}$, then

$$
\begin{aligned}
& \partial^{-1}\left(\psi_{\mu}(\tilde{t}, z), \sqrt{b-1}\right)\left(\psi_{\mu}(t, z),(-)^{\mu+1} \sqrt{-b} e^{-z}\right) \\
& =\partial^{-1}\left(\psi_{\mu}(\tilde{t}, z), \sqrt{b-1}\right)\left(\psi_{\mu}(t, z),(-)^{\mu+1} \sqrt{-b}\left(e^{-z}+w(z)\right)\right) \\
& =\left(\psi_{\mu}(\tilde{t}, z), \sqrt{b-1}\right)\left(\psi_{\mu}(\tilde{t}, z), \sqrt{b-1}\right)^{-1} \partial^{-1}\left(\psi_{\mu}(\tilde{t}, z), \sqrt{b-1}\right) \\
& \cdot\left(\psi_{\mu}(t, z),(-)^{\mu+1} \sqrt{-b}\left(e^{-z}+w(z)\right)\right) \\
& =\left(\psi_{\mu}(\tilde{t}, z), \sqrt{b-1}\right)\left(\psi_{W_{\mu}+\mathbb{C} z h_{2}(z)}(t, z),(-)^{\mu+1} \sqrt{-b}\left(e^{-z}+w(z)\right)\right) \\
& =\left(\psi_{\mu}(\tilde{t}, z), \sqrt{b-1}\right)\left(\psi_{W_{\mu}+\mathbb{C} z h_{2}(z)}(t, z),(-)^{\mu+1} \sqrt{-b}\left(\frac{r_{0}(-z)}{b}+b_{1} r_{1}(-z)\right)\right) .
\end{aligned}
$$

Using (8.23) and (8.30) we find that

$$
\begin{equation*}
\partial^{-1}\left(\psi_{\mu}(\tilde{t}, z), \sqrt{b-1}\right)\left(\psi_{\mu}(t, z),(-)^{\mu+1} \sqrt{-b} e^{-z}\right)=-\sqrt{\frac{b-1}{-b}} \frac{\tau_{W^{\prime \prime \prime}}(t)}{\tau_{\mu}(t)} \tag{8.32}
\end{equation*}
$$

where

$$
\begin{align*}
\tau_{W^{\prime \prime \prime}}(t)=W\left(R_{2}^{\mu}(t)-\frac{R_{1}^{\mu}(t)}{1}, R_{3}^{\mu}(t)\right. & -\frac{R_{2}^{\mu}(t)}{2}, \ldots, R_{\mu}^{\mu}(t)  \tag{8.33}\\
& \left.-\frac{R_{\mu-1}^{\mu}(t)}{\mu-1}, R_{0}^{\mu}(t)+b b_{1} R_{1}^{\mu}(t)\right) .
\end{align*}
$$

Now comparing (5.1), (5.5), (8.32) and (8.33) we see that

$$
b_{1}=0
$$

For this $b_{1}=0$, the tau-function $\tau_{W^{\prime \prime \prime}}$ corresponds to the following point in the Grassmannian:

$$
\begin{align*}
W^{\prime \prime \prime}= & \left\{f(z) \in H_{-\mu} \mid\left(f(z), r_{0}(-z)\right)=0\right.  \tag{8.34}\\
& \text { and } \left.\left(f(z), r_{i}(-z)-\frac{r_{i-1}(-z)}{i-1}\right)=0 \text { for } \quad i=2,3 \ldots, \mu\right\} .
\end{align*}
$$

Hence, using the fact that $\alpha=\sqrt{b-1}$ and $a=(-)^{\mu+1} \sqrt{-b}$ one finds that

$$
\beta_{13}(s)=\partial^{-1}\left(\psi_{\mu}(\tilde{s}, z), \sqrt{b-1}\right)\left(\psi_{\mu}(s, z),(-)^{\mu+1} \sqrt{-b} e^{-z}\right)
$$

We now calculate the squared eigenfunction potential in a different way. Let

$$
w(z)=\sum_{i=1}^{\mu} a_{i} r_{i}(-z)+\sum_{j>\mu} a_{j} z^{j},
$$

be an arbitrary element of $W_{\mu}^{\perp}$, a straightforward calculation shows that

$$
\begin{aligned}
& \partial^{-1}\left(\psi_{\mu}(\tilde{t}, z),(-)^{\mu+1} \sqrt{-b} e^{-z}\right)\left(\psi_{\mu}(t, z), \sqrt{b-1}\right) \\
& \quad=\partial^{-1}\left(\psi_{\mu}(\tilde{t}, z),(-)^{\mu+1} \sqrt{-b} e^{-z}\right)\left(\psi_{\mu}(t, z), \sqrt{b-1}(1+w(z))\right) \\
& \quad=\left(\psi_{\mu}(\tilde{t}, z),(-)^{\mu+1} \sqrt{-b} e^{-z}\right)\left(\psi_{W_{\mu}+\mathbb{C} z h_{1}(z)}(t, z), \sqrt{b-1}\left(1+a_{1} r_{1}(-z)\right)\right) .
\end{aligned}
$$

Using (8.23) and (8.30) we find that

$$
\begin{align*}
\partial^{-1}\left(\psi_{\mu}(\tilde{t}, z)\right. & \left.(-)^{\mu+1} \sqrt{-b} e^{-z}\right)\left(\psi_{\mu}(t, z), \sqrt{b-1}\right)  \tag{8.35}\\
& =\sqrt{\frac{b-1}{-b}} \frac{\tau_{W^{\prime}}(\tilde{t}) \tau_{W^{\prime \prime \prime \prime}}(t)}{\tau_{\mu}(\tilde{t}) \tau_{W_{\mu}+\mathbb{C} z h_{1}(z)}(t)}=\sqrt{-b(b-1)} \frac{\tau_{W^{\prime \prime \prime \prime}}(t)}{\tau_{\mu}(t)}
\end{align*}
$$

where

$$
\begin{equation*}
\tau_{W^{\prime \prime \prime \prime}}(t)=W\left(R_{2}^{\mu}(t), R_{3}^{\mu}(t), \ldots, R_{\mu}^{\mu}(t), S_{\mu-1}(t)+a_{1} R_{1}^{\mu}(t)\right) \tag{8.36}
\end{equation*}
$$

This is the tau-function corresponding to the following point of the Grassmannian

$$
\begin{align*}
W^{\prime \prime \prime \prime}=\left\{f(z) \in H_{-\mu} \mid\right. & \left(f(z), 1+a_{1} r_{1}(-z)\right)=0  \tag{8.37}\\
& \text { and } \left.\left(f(z), r_{i}(-z)\right)=0 \quad \text { for } \quad i=2,3 \ldots, \mu\right\} .
\end{align*}
$$

Hence

$$
\begin{align*}
& \partial^{-1}\left(\psi_{\mu}(\tilde{t}, z),(-)^{\mu+1} \sqrt{-b} e^{-z}\right)\left(\psi_{\mu}(t, z), \sqrt{b-1}\right)  \tag{8.38}\\
& =\sqrt{-b(b-1)}\left(\frac{W\left(R_{2}^{\mu}(t), R_{3}^{\mu}(t), \ldots, R_{\mu}^{\mu}(t), S_{\mu-1}(t)\right)}{W\left(R_{1}^{\mu}(t), R_{2}^{\mu}(t), \ldots, R_{\mu}^{\mu}(t)\right)}-(-)^{\mu} a_{1}\right) .
\end{align*}
$$

It is not clear yet what the value of $a_{1}$ one should take.
We now put all $t_{i}=0$ for $i>1$, and write $f(x)$ for $f(x, 0,0, \ldots)$. Comparing (8.32) and (8.35), we see that

$$
\begin{equation*}
b \tau_{W^{\prime \prime \prime \prime}}(x)=\tau_{W^{\prime \prime \prime}}(x) \tag{8.39}
\end{equation*}
$$

To calculate $a_{1}$ we substitute $x=0$. We find that

$$
\begin{align*}
\tau_{\mu}(0)=\tau_{W_{\mu}}(0) & =\operatorname{det}\left(\left(z^{i-\mu-1}, r_{j}(-z)\right)\right)_{1 \leqslant i, j \leqslant \mu} \\
& =\operatorname{det}\left(\frac{(-)^{\mu-i} b}{(\mu+j-i)!}\right)_{1 \leqslant i, j \leqslant \mu} \\
& =(-)^{\frac{\mu(\mu-1)}{2}} b^{\mu} \operatorname{det}\left(\frac{1}{(\mu+j-i)!}\right)_{1 \leqslant i, j \leqslant \mu} \\
& =(-)^{\frac{\mu(\mu-1)}{2}} b^{\mu} \mu S_{\mu, \mu, \ldots, \mu}^{(\mu)}(1,0,0, \ldots)  \tag{8.40}\\
& =(-)^{\frac{\mu(\mu-1)}{2}} b^{\mu} \mu \frac{\prod_{i=1}^{\mu-1}(i!)^{2}}{\prod_{i=1}^{2 \mu-1} i!} .
\end{align*}
$$

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In a similar way we find that $\tau_{W^{\prime \prime \prime}}(0)=\tau_{\mu}(0)$ and that

$$
\begin{equation*}
\tau_{W^{\prime \prime \prime \prime}}(0)=(-)^{\frac{\mu(\mu-1)}{2}}\left(b^{\mu-1}-(-)^{\mu} a_{1} b^{\mu}\right) \mu \frac{\prod_{i=1}^{\mu-1}(i!)^{2}}{\prod_{i=1}^{2 \mu-1} i!} . \tag{8.41}
\end{equation*}
$$

Comparing all the results (8.39)-(8.41) we conclude that

$$
a_{1}=0 .
$$

Since we know that $\sum_{i=1}^{3} \omega_{i}^{2}(x)$ is equal to a constant, it suffices to calculate this value for $x=0$. We find that

$$
\begin{aligned}
& \omega_{1}(0)=\beta_{32}(0)=\frac{1}{\sqrt{-b}} \frac{\tau_{W^{\prime}}(0)}{\tau_{\mu}(0)} \\
&=\frac{1}{\sqrt{-b}} \frac{(-)^{\frac{\mu(\mu-1)}{2}+1} b^{\mu} S_{\mu-1, \mu-1, \ldots, \mu-1}^{(\mu+1)}(1,0,0, \ldots)}{(-)^{\frac{\mu(\mu-1)}{2}} b^{\mu} S_{\mu, \mu, \ldots, \mu}^{(\mu)}(1,0,0, \ldots)} \\
&=-\frac{1}{\sqrt{-b}} \mu, \\
& \omega_{2}(0)=-\beta_{13}(0)=-\sqrt{-b(b-1)} \frac{\tau_{W^{\prime \prime \prime \prime}}(0)}{\tau_{\mu}(0)} \\
&=-\sqrt{-b(b-1)} \frac{(-)^{\frac{\mu(\mu-1)}{2}} b^{\mu-1} S_{\mu+1, \mu+1, \ldots, \mu+1}^{(\mu-1)}(1,0,0, \ldots)}{(-)^{\frac{\mu(\mu-1)}{2}} b^{\mu-1} S_{\mu, \mu, \ldots, \mu}^{(\mu)}(1,0,0, \ldots)} \\
&=-\sqrt{-b(b-1)} \frac{\mu}{b}=\sqrt{\frac{b-1}{-b}} \mu, \\
& \omega_{3}(0)=0 \beta_{12}(0)=0 .
\end{aligned}
$$

Hence,

$$
\sum_{i=1}^{3} \omega_{i}^{2}(0)=\left(\frac{1}{\sqrt{-b}} \mu\right)^{2}+\left(\sqrt{\frac{b-1}{-b}} \mu\right)^{2}=-\mu^{2}
$$

and

$$
\begin{equation*}
\sum_{i=1}^{3} \omega_{i}^{2}(x)=-\mu^{2} \tag{8.42}
\end{equation*}
$$

We next calculate $R_{i}^{\mu}(x)$ :

$$
\begin{aligned}
R_{i}^{\mu}(x) & =\sum_{k=0}^{i-1} \frac{(-1)^{k-i}}{k!} \frac{x^{\mu+i-k-1}}{(\mu+i-k-1)!}+b \sum_{k=i}^{\mu+i-1} \frac{(-1)^{k-i}}{k!} \frac{x^{\mu+i-k-1}}{(\mu+i-k-1)!} \\
& =(-)^{i} \frac{(x-1)^{\mu+i-1}}{(\mu+i-1)!}+(-)^{\mu-1}(b-1) \sum_{j=0}^{\mu-1} \frac{(-x)^{j}}{j!(\mu+i-j-1)!}
\end{aligned}
$$

Combining all the previous results we find:
Theorem 8.1. - The expressions

$$
y(x)=x \frac{ \pm(x-1) \mu \omega_{1} \omega_{2} \omega_{3}+x \omega_{1}^{2} \omega_{2}^{2}+\omega_{1}^{2} \omega_{3}^{2}}{(x-1)^{2} \omega_{2}^{2} \omega_{3}^{2}+x^{2} \omega_{1}^{2} \omega_{2}^{2}+\omega_{1}^{2} \omega_{3}^{2}}
$$

and

$$
y(x)=-x \frac{x\left(\omega_{1} \omega_{2} \mp \mu \omega_{3}\right)^{2}+\left(\omega_{1} \omega_{3} \pm \mu \omega_{2}\right)^{2}}{\left(\omega_{3}^{2}+\mu^{2}+x\left(\omega_{2}^{2}+\mu^{2}\right)\right)^{2}+4 x \mu^{2} \omega_{1}^{2}}
$$

for $\mu=1,2, \ldots$, with

$$
\begin{align*}
& \omega_{1}(x)=\sqrt{-b}(1-x) \frac{W\left(R_{2}^{\mu}(x), R_{3}^{\mu}(x), \ldots, R_{\mu}^{\mu}(x)\right)}{W\left(R_{1}^{\mu}(x), R_{2}^{\mu}(x), \ldots, R_{\mu}^{\mu}(x)\right)},  \tag{8.43}\\
& \omega_{2}(x)=-\sqrt{-b(b-1)} \frac{W\left(R_{2}^{\mu}(x), R_{3}^{\mu}(x), \ldots, R_{\mu}^{\mu}(x), \frac{x^{\mu-1}}{(\mu-1)!}\right)}{W\left(R_{1}^{\mu}(x), R_{2}^{\mu}(x), \ldots, R_{\mu}^{\mu}(x)\right)}, \\
& \omega_{3}(x)=\sqrt{b-1} x \frac{W\left(R_{1}^{\mu}(x), R_{2}^{\mu}(x), \ldots, R_{\mu}^{\mu}(x), \frac{x^{\mu-1}}{(\mu-1)!}\right)}{W\left(R_{1}^{\mu}(x), R_{2}^{\mu}(x), \ldots, R_{\mu}^{\mu}(x)\right)}
\end{align*}
$$

are rational solutions of the Painlevé VI equation (1.5) for the parameters

$$
\begin{aligned}
& (\alpha, \beta, \gamma, \delta)=\left(\frac{(1 \mp \mu)^{2}}{2},-\frac{\mu^{2}}{2}, \frac{\mu^{2}}{2}, \frac{1-\mu^{2}}{2}\right), \quad \text { respectively } \\
& (\alpha, \beta, \gamma, \delta)=\left(\frac{(1 \pm 2 \mu)^{2}}{2}, 0,0, \frac{1}{2}\right)
\end{aligned}
$$

The $\omega_{i}$ separately satisfy the time dependent Euler top equations (1.11).
The above results are clearly valid for $\mu>1$. We will now treat the case $\mu=1$ separately. In that case $W_{1}$ corresponds to the 1 -vector 1-constrained KP hierarchy and

$$
\tau_{1}(t)=R_{1}^{1}(t)=-S_{1}(t)+b S_{0}(t)=b-x .
$$

We use the same expressions for the $\beta_{i j}(x)$ in terms of the Wronskian determinants as in the case $\mu>1$, viz.,

$$
\begin{aligned}
\beta_{23}(x)= & \frac{1}{\sqrt{-b}} \frac{-b}{b-x}, \quad \beta_{12}(x)=\sqrt{b-1} \frac{1}{b-x} \\
& \beta_{13}(x)=\sqrt{-b(b-1)} \frac{1}{b-x}
\end{aligned}
$$

This leads to the $\omega_{i}$ 's (1.35) for $\mu^{2}=1$.

Remark 8.1. - From the rational solutions (8.43) for the time dependent Euler top equations for the values $\mu=1,2,3, \ldots$ one can recover the expression of the $\omega_{i}$ in the $u_{i}, i=1,2,3$, by just substituting:

$$
x=\frac{u_{2}-u_{1}}{u_{3}-u_{1}}
$$

in $V(x)$, i.e., in all $\omega_{i}(x)$. Using (2.8) one finds expressions for the rotation coefficients $\beta_{i j}(u)$ that satisfy (2.1)-(2.3).

Finally we give as an example the explicit $\omega_{i}$ 's for $\mu=3$ :

$$
\omega_{i}=\frac{N_{i}(x)}{D(x)}
$$

where

$$
\begin{aligned}
& N_{1}(x)=3 \sqrt{-b}(1-x)\left(b^{2}-8 b^{2} x+18 b x^{2}+10 b^{2} x^{2}-56 b x^{3}+70 b x^{4}-56 b x^{5}\right. \\
&\left.+10 x^{6}+18 b x^{6}-8 x^{7}+x^{8}\right) \\
& N_{2}(x)=- 3 \sqrt{-b(b-1)}\left(b^{2}-18 b x^{2}+52 b x^{3}-60 b x^{4}+24 b x^{5}+10 x^{6}-12 x^{7}+3 x^{8}\right) \\
& N_{3}(x)=3 \sqrt{b-1} x\left(3 b^{2}-12 b^{2} x+10 b^{2} x^{2}+24 b x^{3}-60 b x^{4}+52 b x^{5}-18 b x^{6}+x^{8}\right) \\
& D(x)=b^{3}-9 b^{2} x+36 b^{2} x^{2}-84 b^{2} x^{3}+36 b x^{4}+90 b^{2} x^{4}-90 b x^{5}-36 b^{2} x^{5} \\
&+84 b x^{6}-36 b x^{7}+9 b x^{8}-x^{9} .
\end{aligned}
$$

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